

横浜市立大学大学院
ナノシステム科学専攻
物理博士 ミケレット・ルジェロ

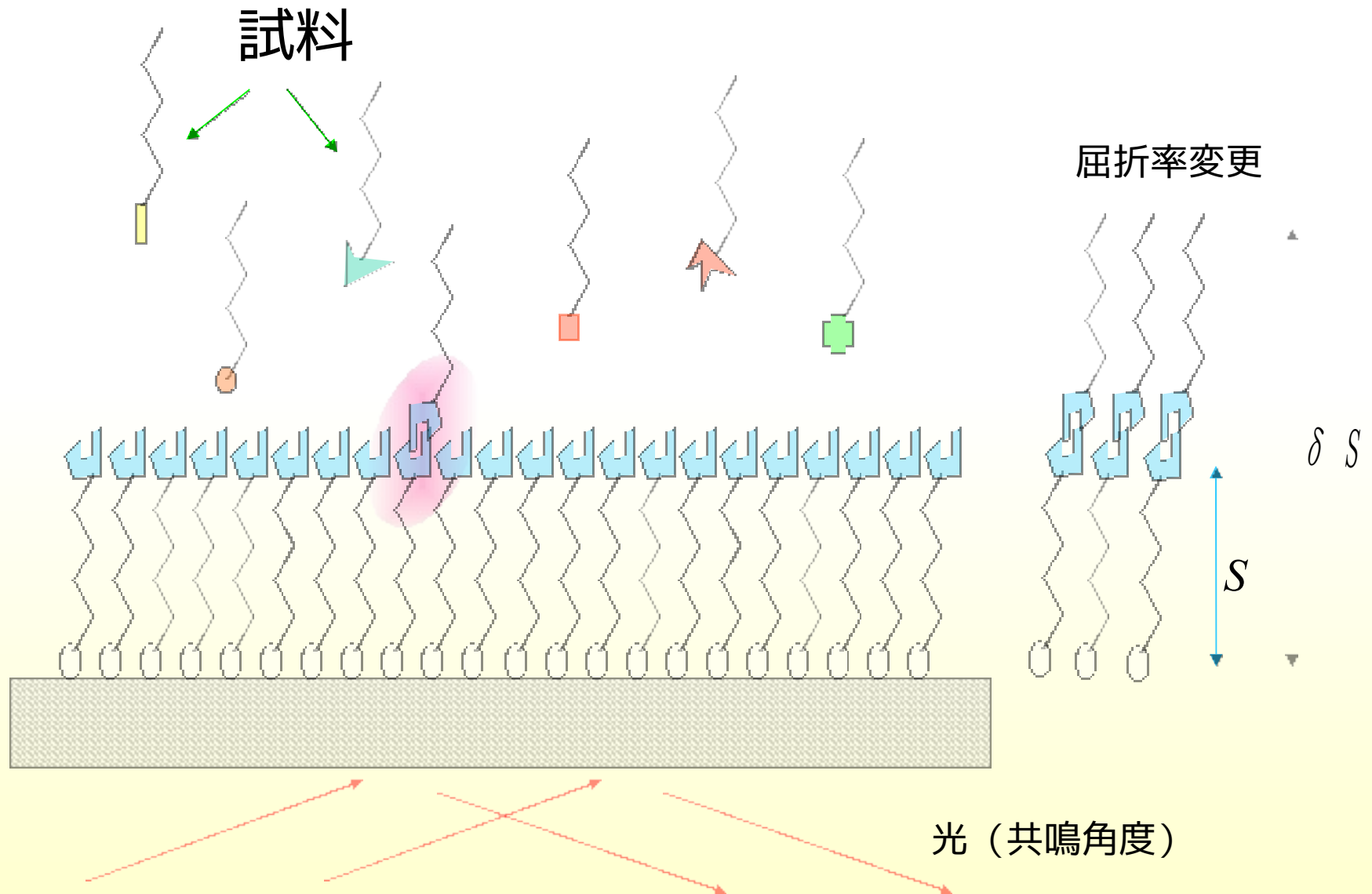
知覚情報科学

e-mail:ruggero@yokohama-cu.ac.jp

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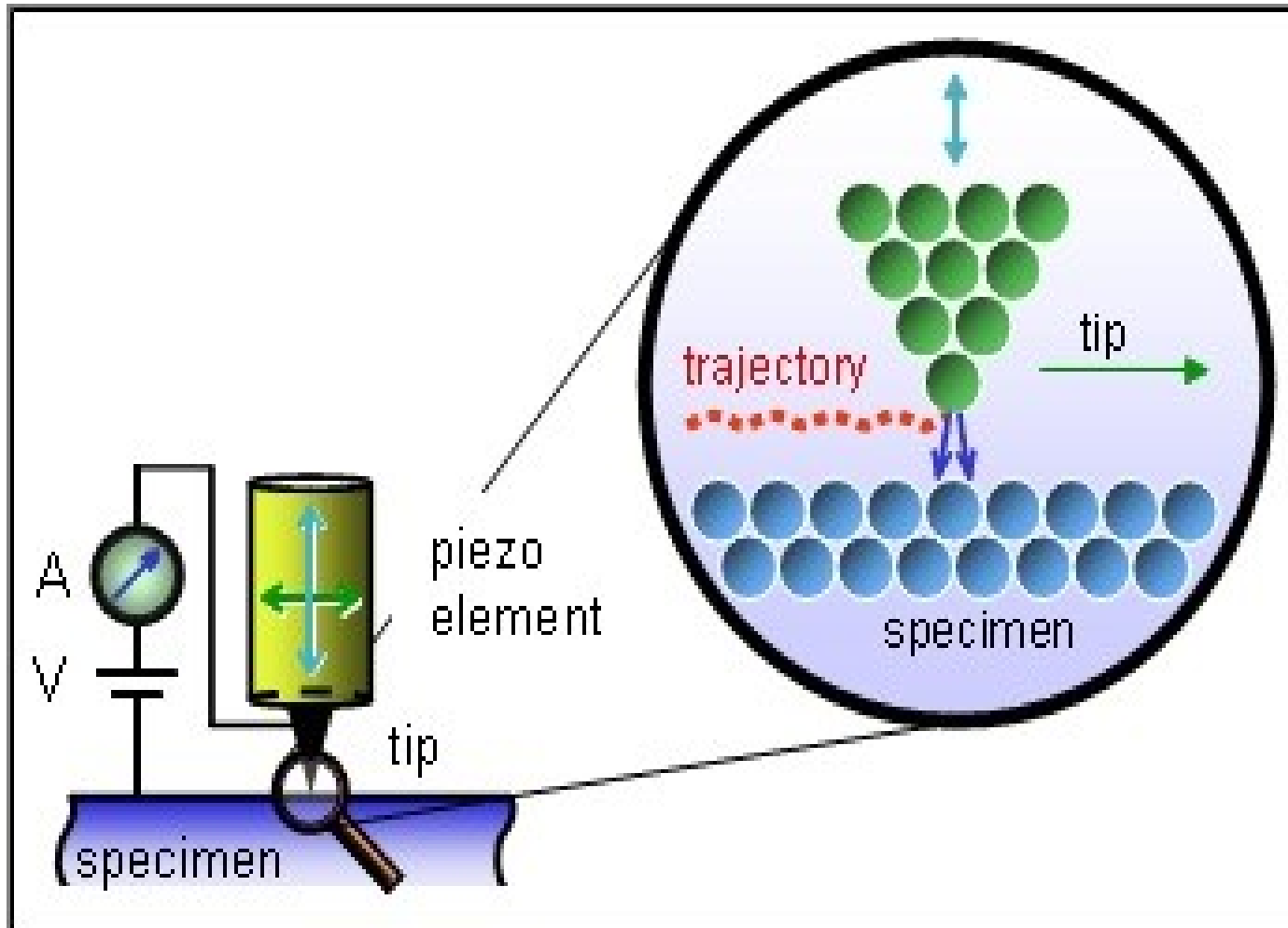
後期2010年

表面プラズモン共鳴を用いたバイオセンシング技術の観念

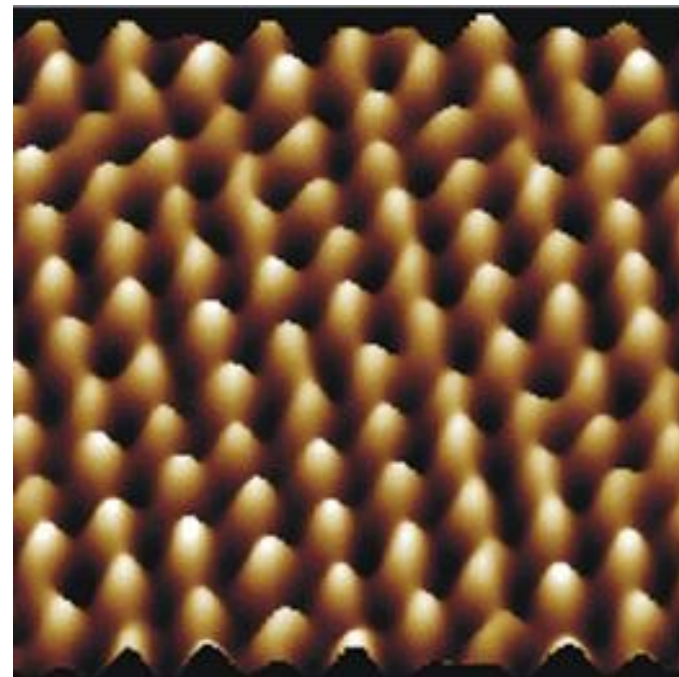
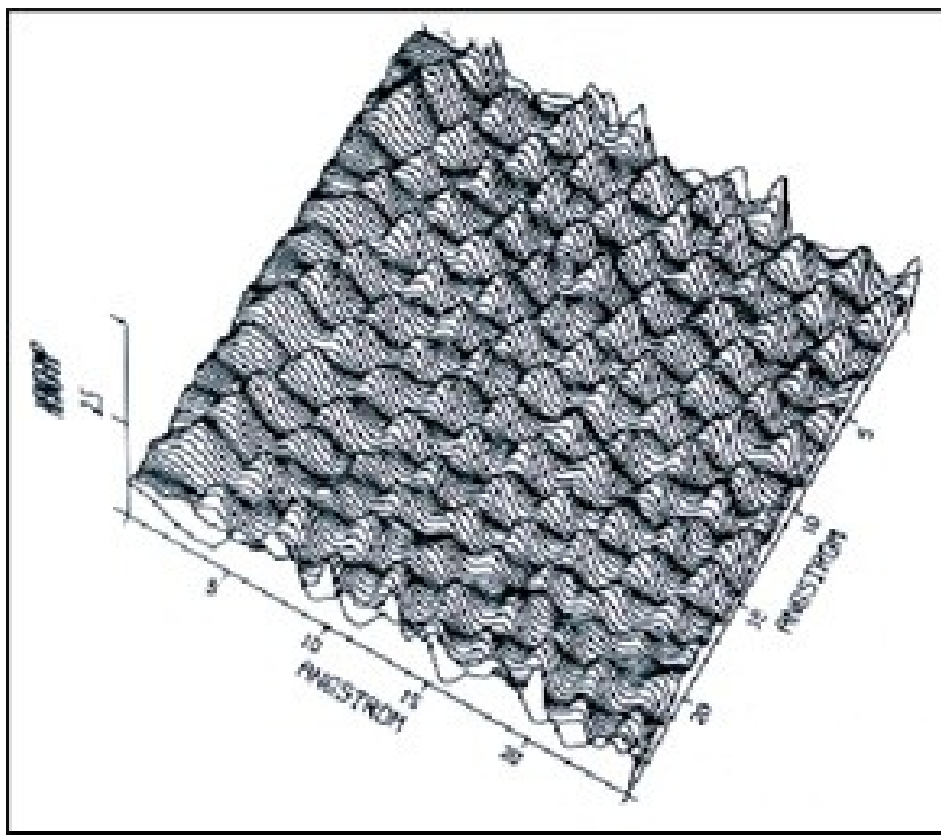


Scanning Tunneling Microscope (STM)

電子トンネル顕微鏡



原子を見ました！

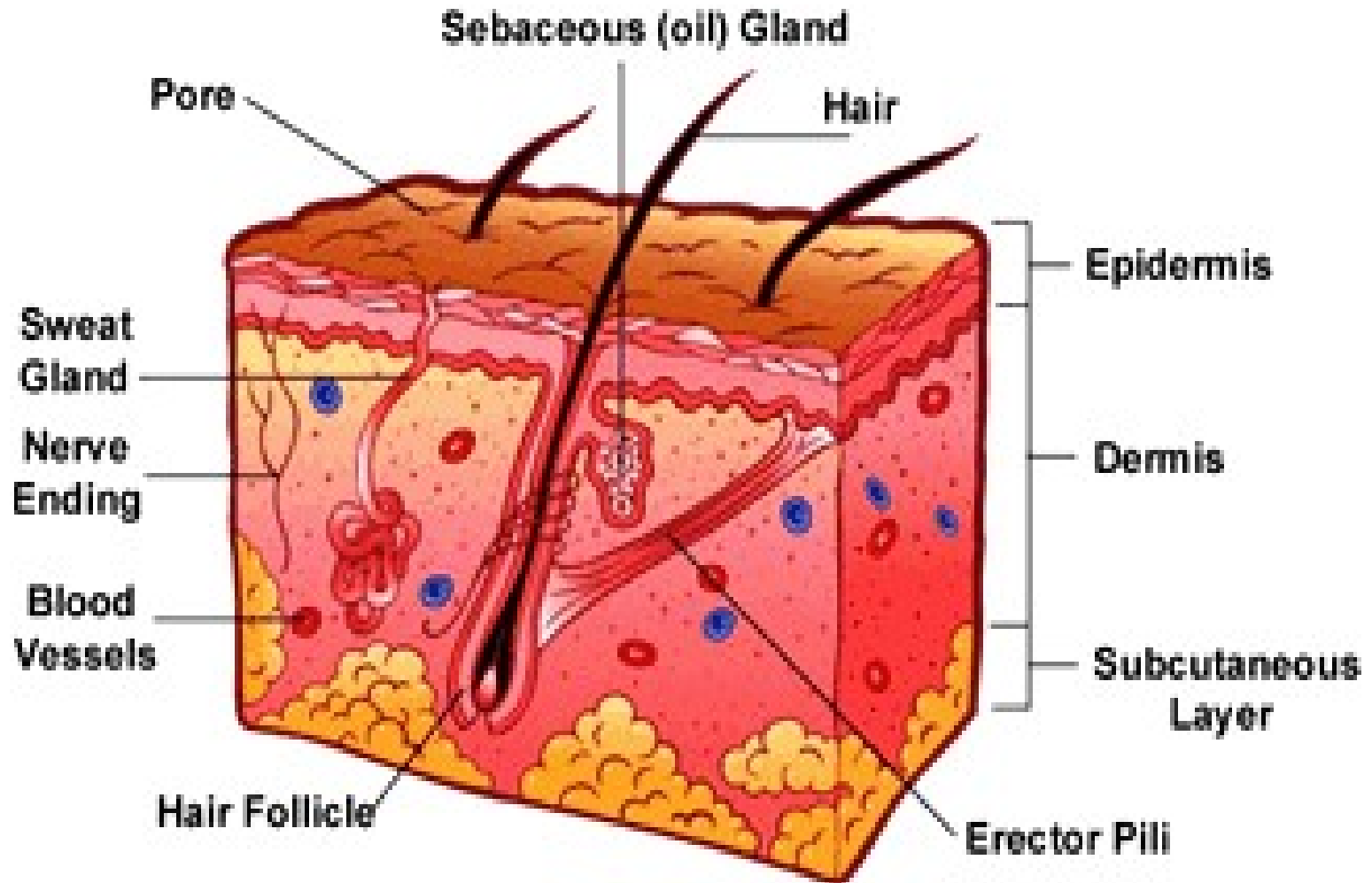


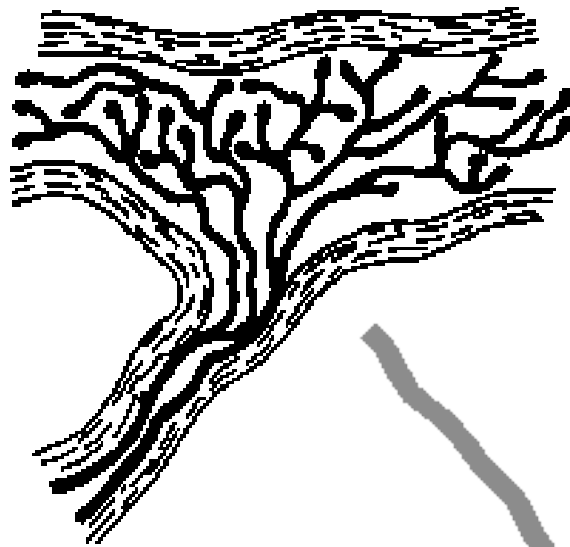
Graphite HOPG

THE SKIN: the TOUCH sense (触覚)

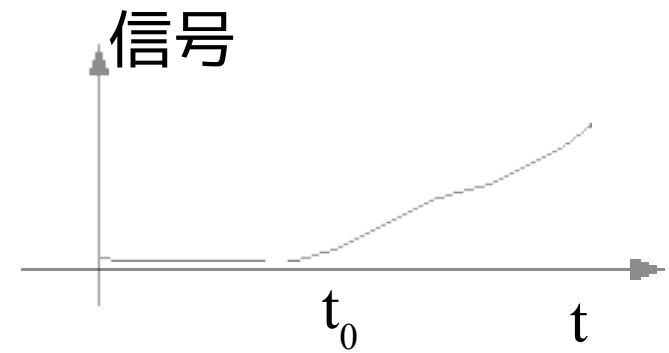


THE SKIN: the TOUCH sense (触覚)

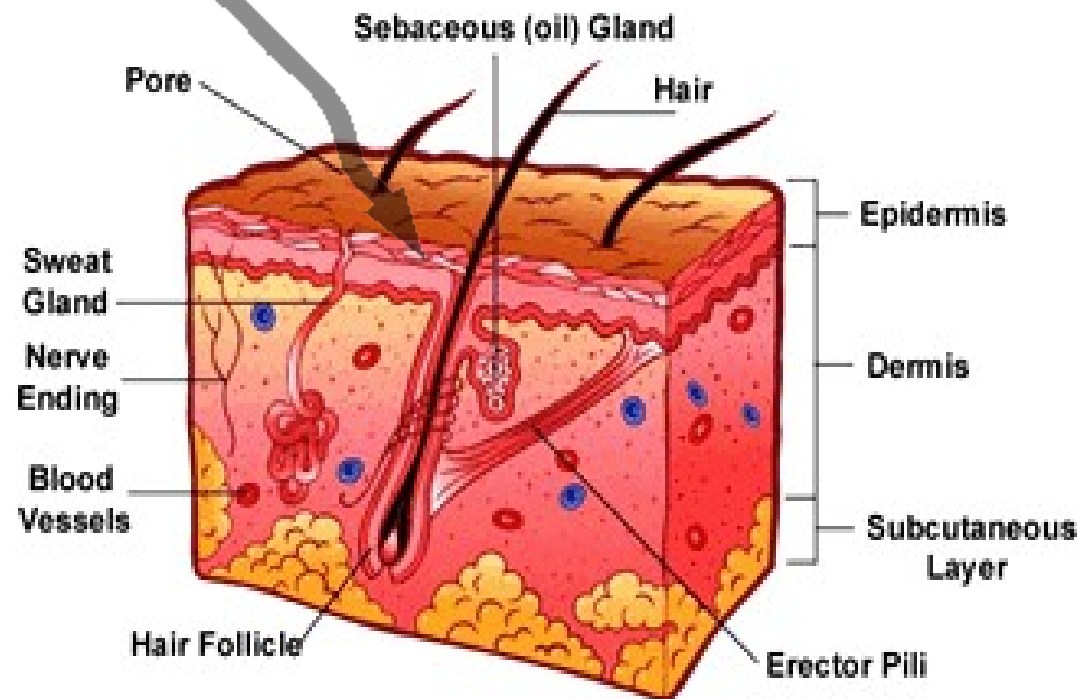


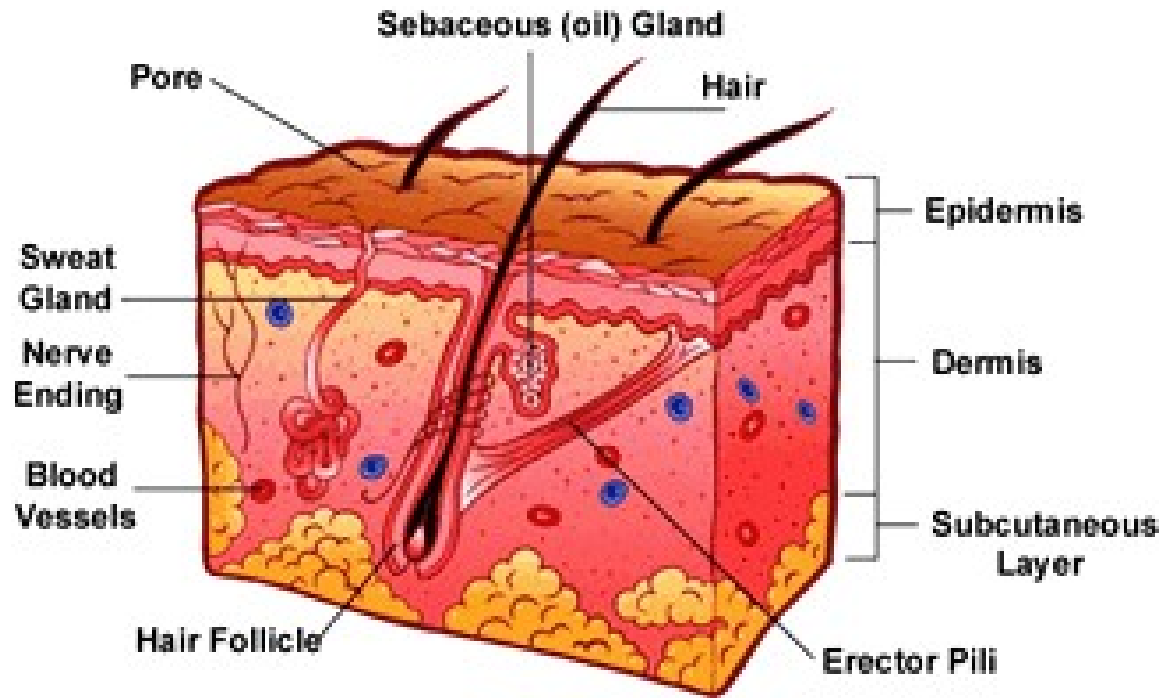


Ruffini Endings



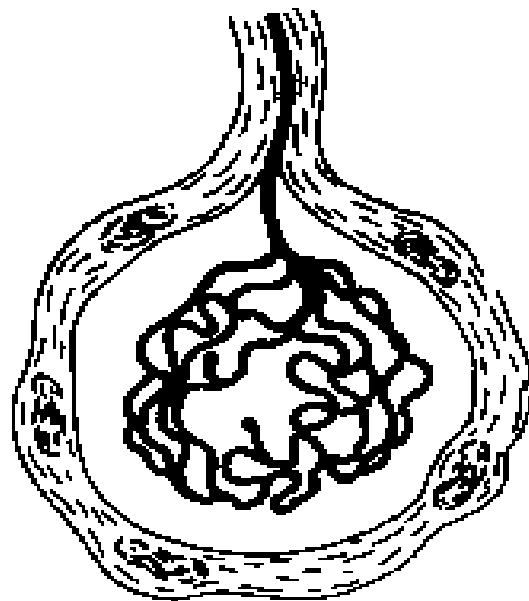
スロー
圧力センサー





A mechanical deformation of the sensory dendrite causes a depolarization to occur within the dendrite. This dendrite is at the tip of a unipolar neuron; The sensory dendrite is embedded within the sensor corpuscle. Any depolarization that is large enough in the dendrite itself will cause an action potential to be generated at the trigger zone. This action potential will run all the way down the axon and reach the brain.

圧力センサー

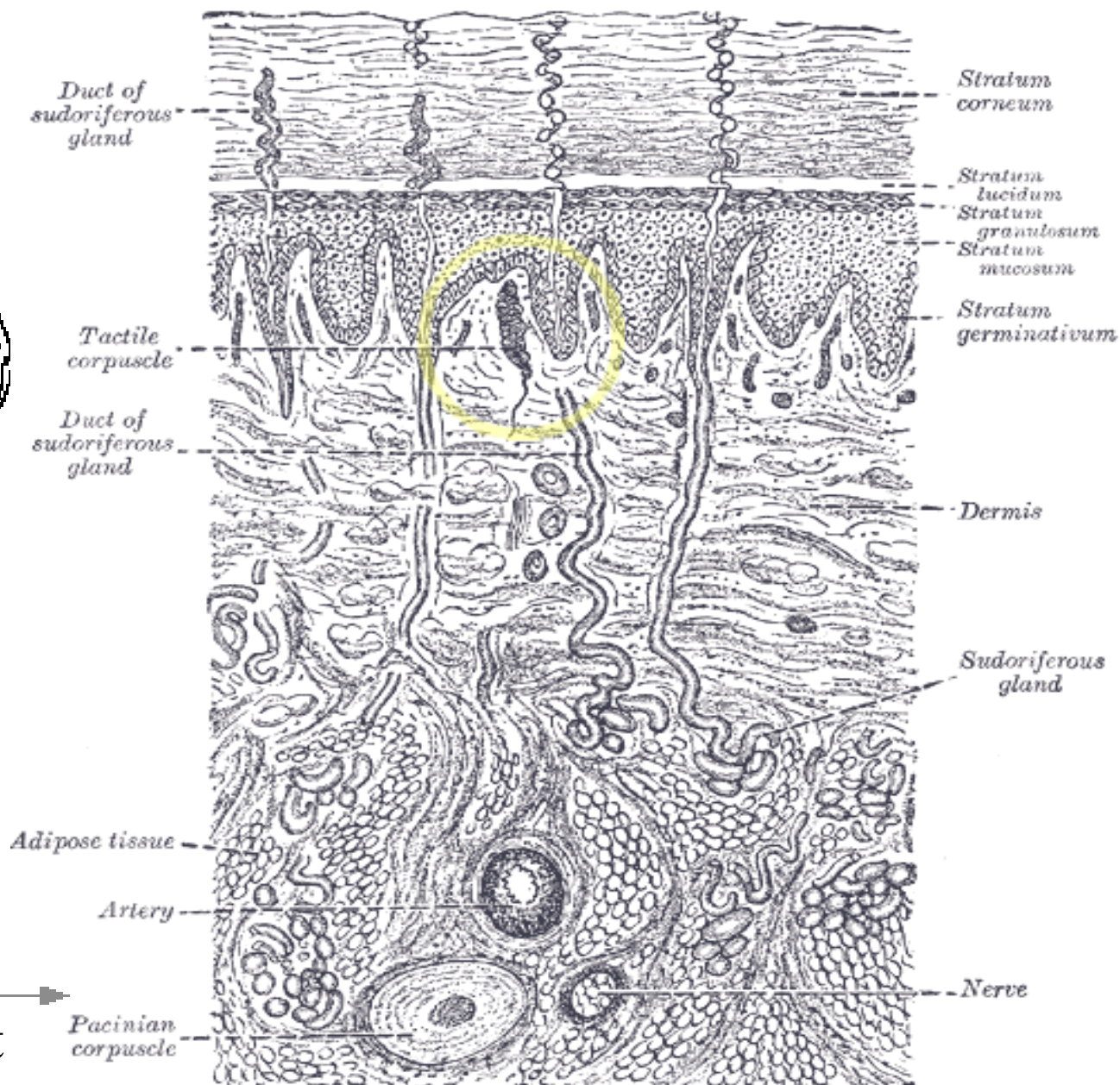


Krause corpuscle

信号

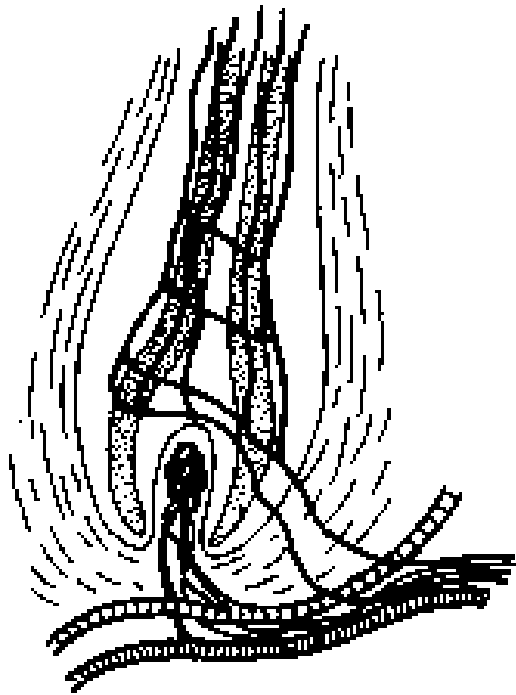
t_0

t

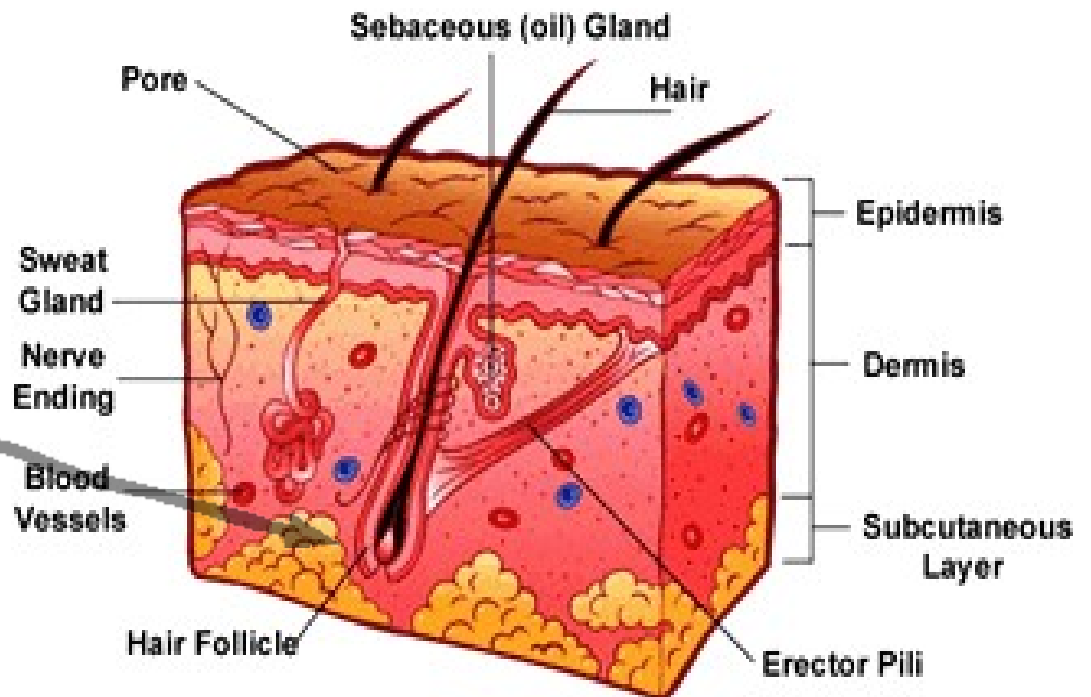


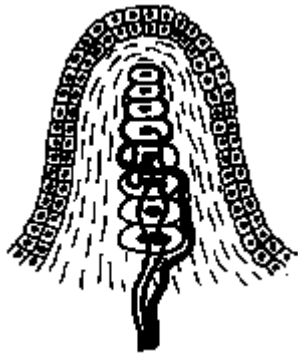
Responds to hair displacement.

Wraps around hair follicle in, of course, hairy skin.



Hair
Follicle
Ending





最大感
度：20-40
Hz

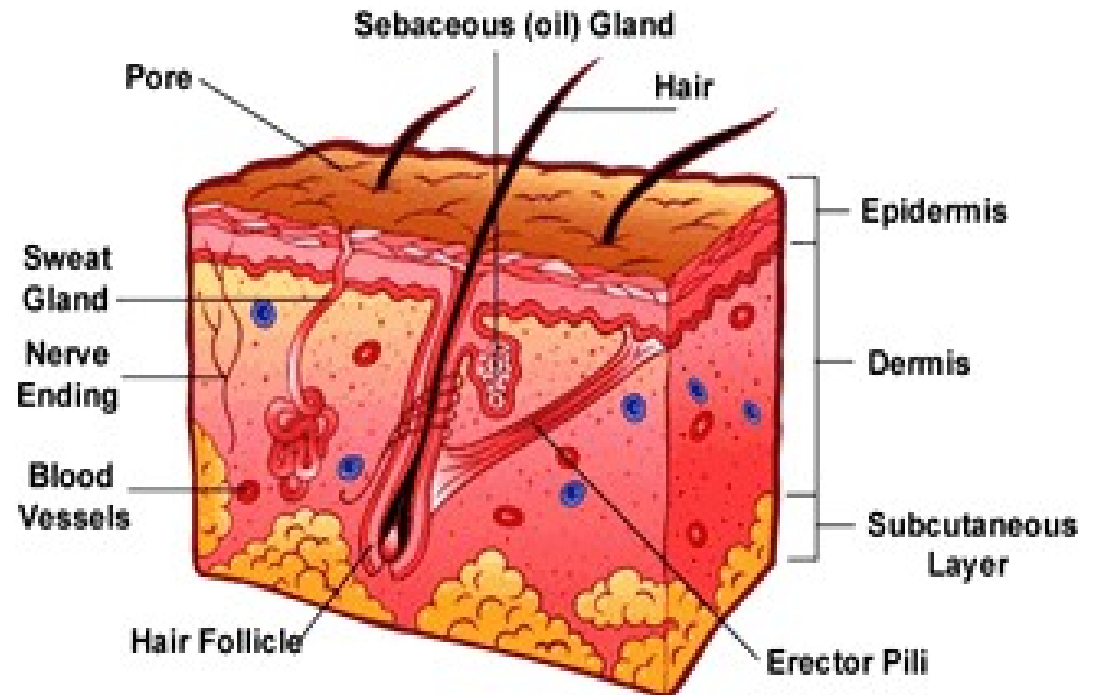
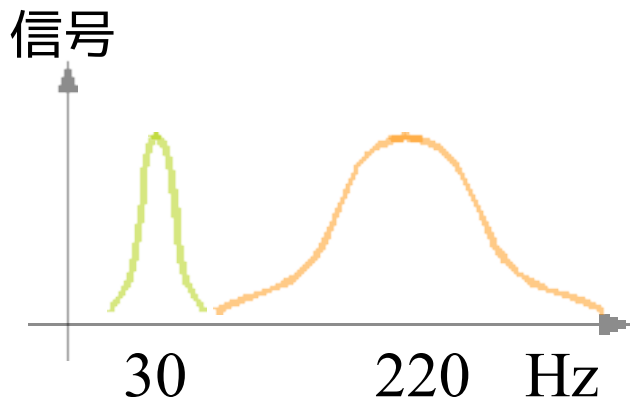
Meissner corpuscle

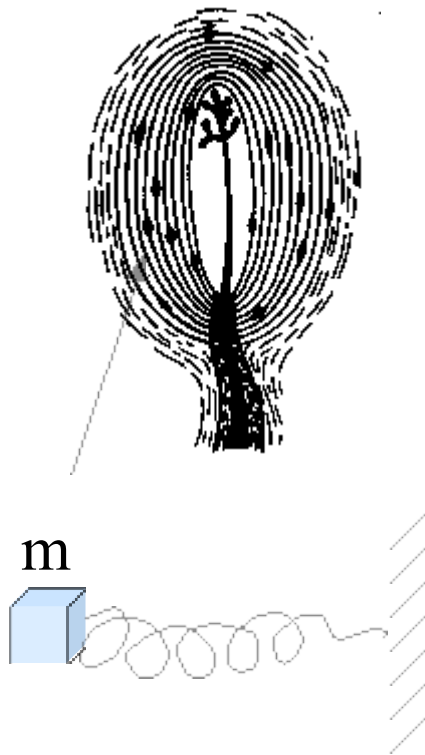


最大感
度：150-
300 Hz

Pacinian corpuscle

振動セン
サー





$$F = -kx$$

$$m a = -k x$$

$$m \frac{d^2 x}{dt^2} = -k x$$

Wave equation



$$\frac{d^2 x}{dt^2} + \frac{k}{m} x = 0$$

Wave function



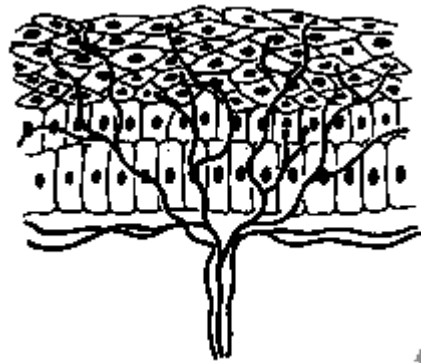
$$x = -\sin(\omega t)$$

pulsation



$$\omega = \sqrt{\frac{k}{m}} = (2 \pi f)$$

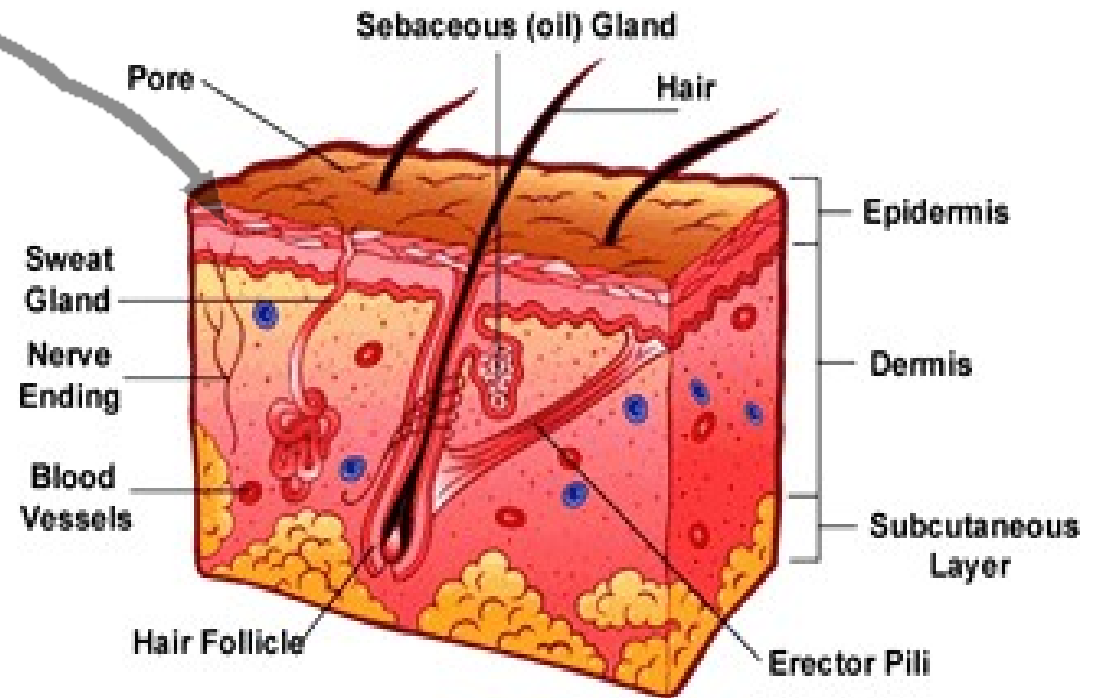
Frequency depends on material “m” and “k”



温度センサー
圧力センサー
化学センサー

Free nerve endings

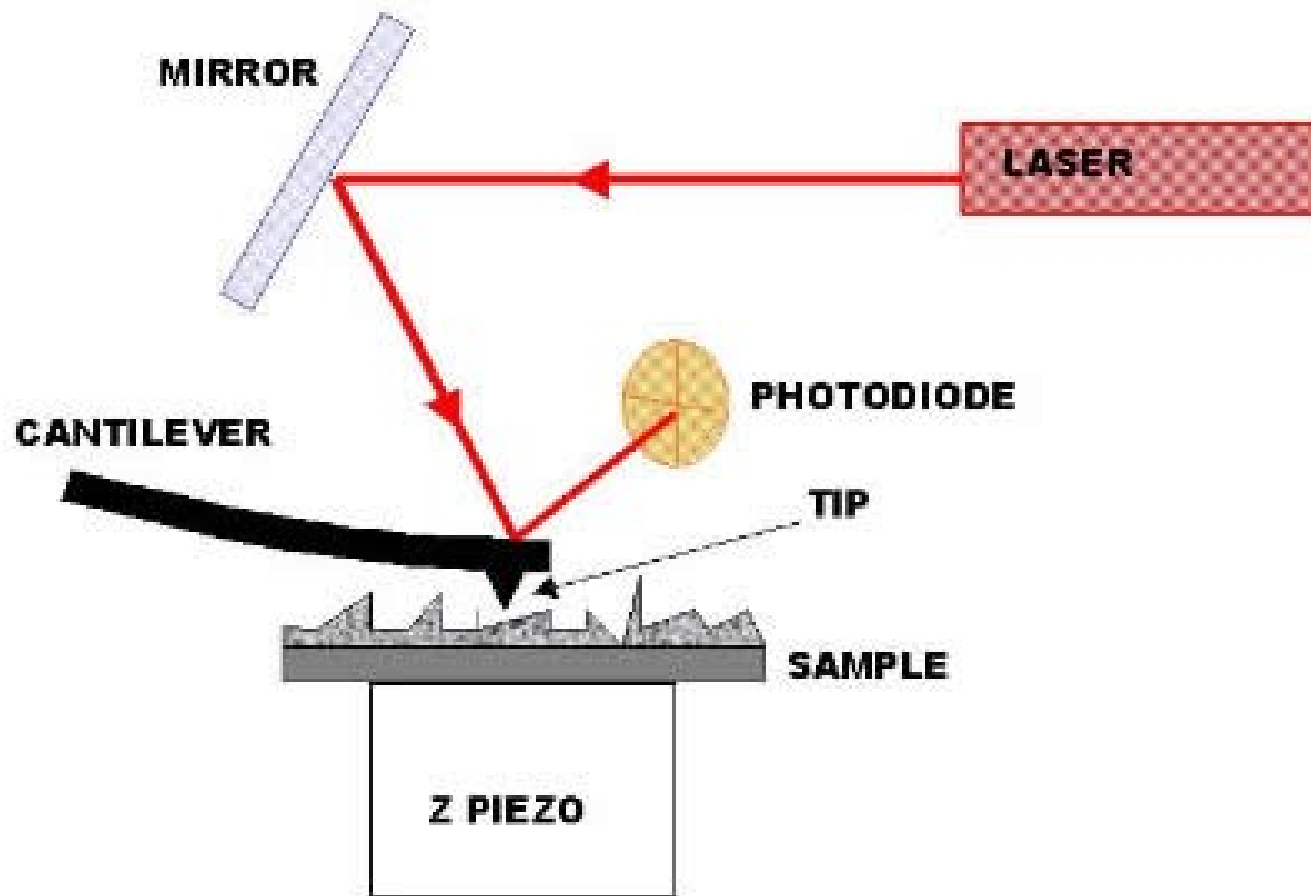
Different types of free nerve endings that respond to mechanical, thermal or noxious stimulation.



先端人工触覚センサー：原子間力顕微鏡

(AFM: Atomic Force Microscope)





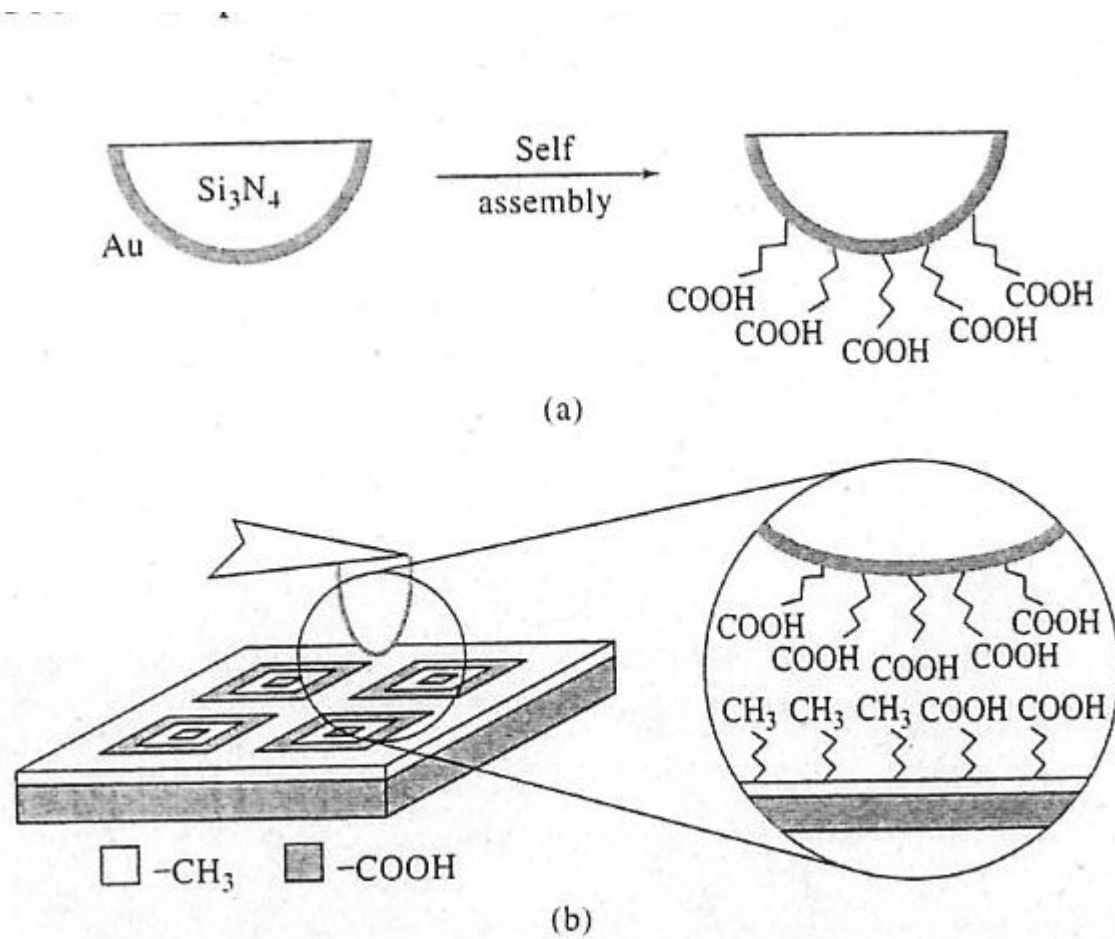
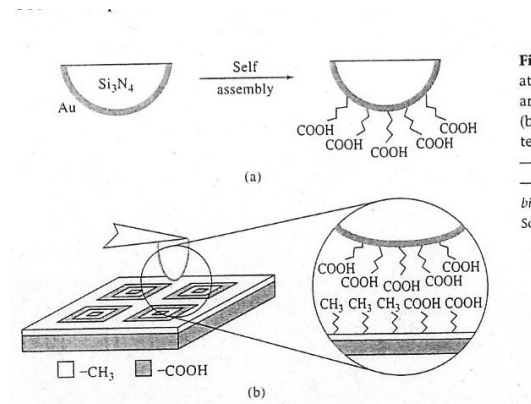
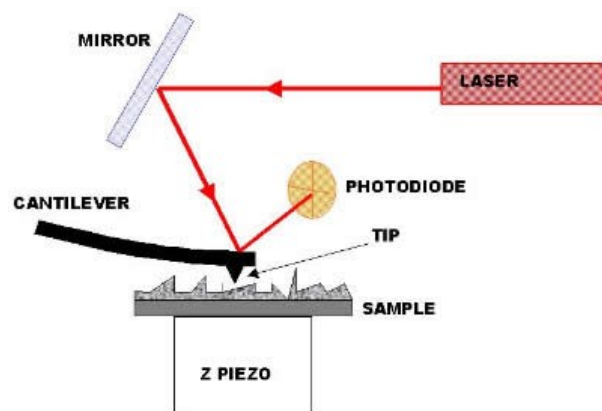
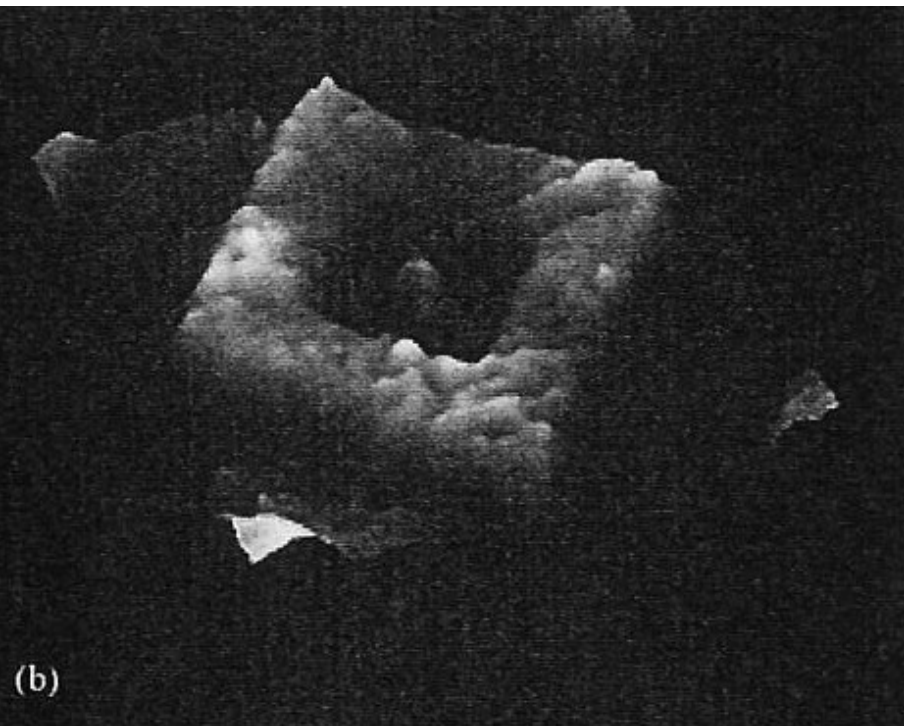
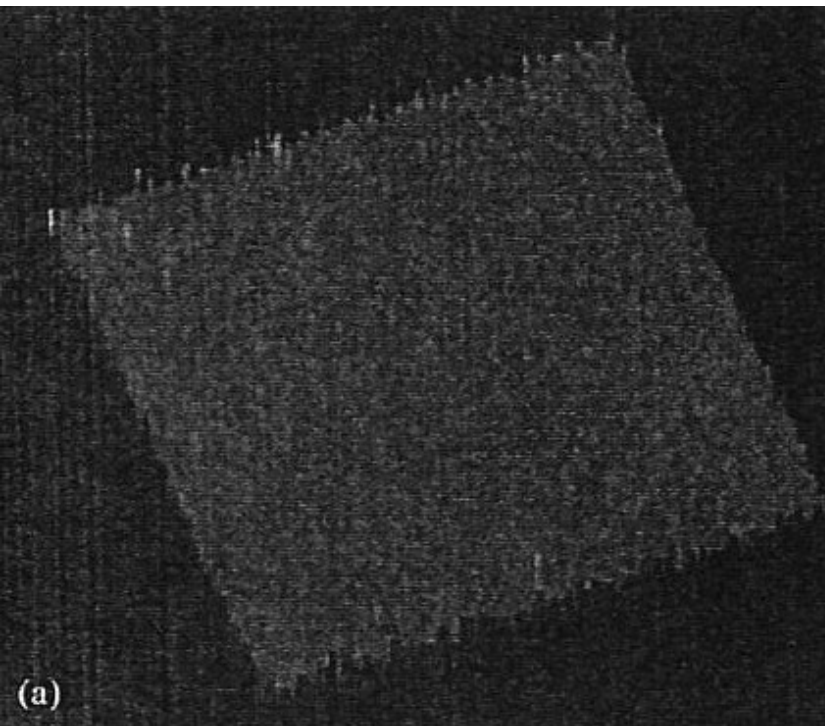
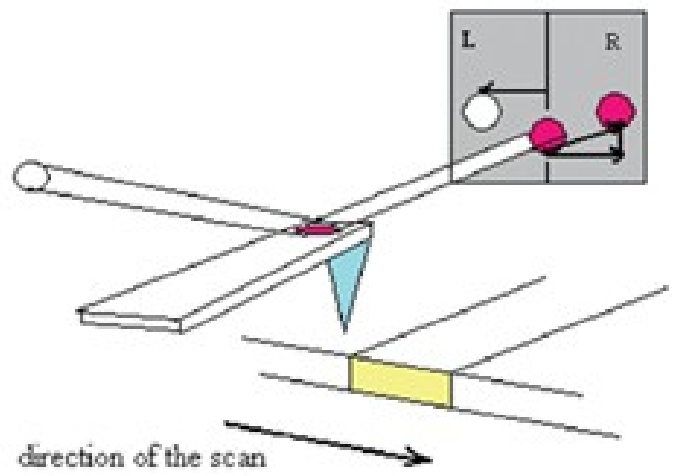
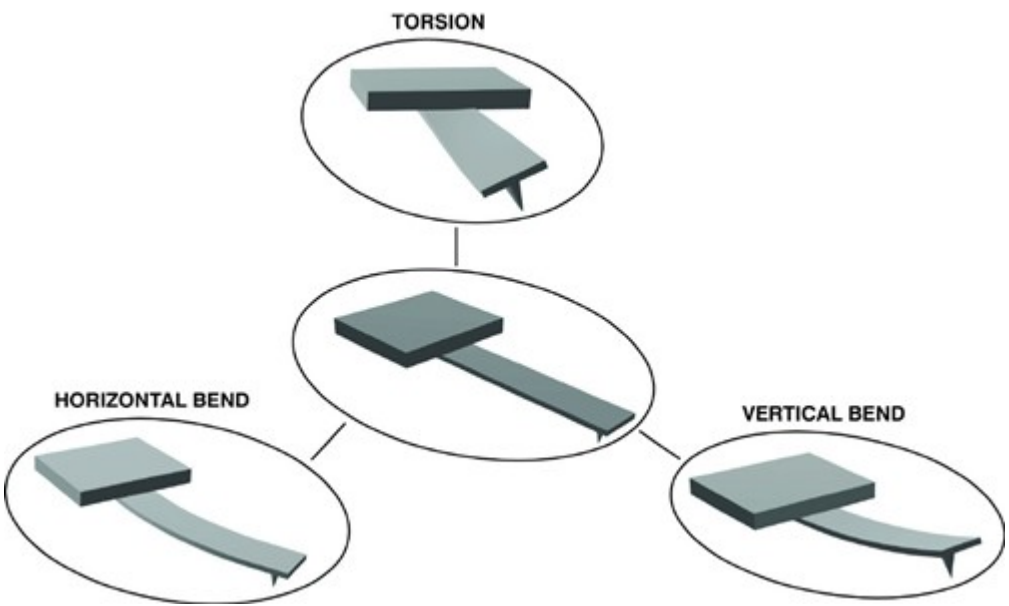


Fig. 1. (a) Self-assembly of a molecular monolayer on a Si_3N_4 surface. (b) Schematic representation of the molecular monolayer structure.



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OMCL-AC160BN
series

Rectangular cantilevers with thin tetrahedral tips

Tip location: Just on end of cantilever

Chip size of silicon cantilever

One cantilever is extended from side edge of each chip

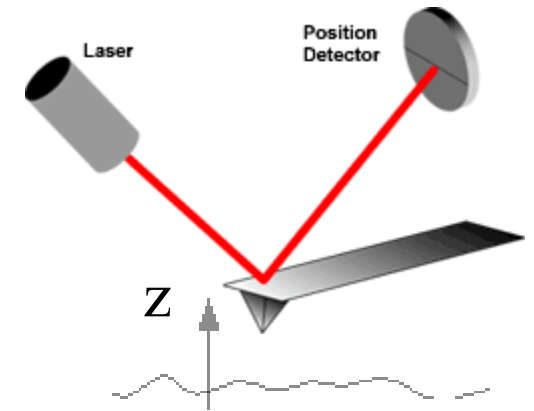
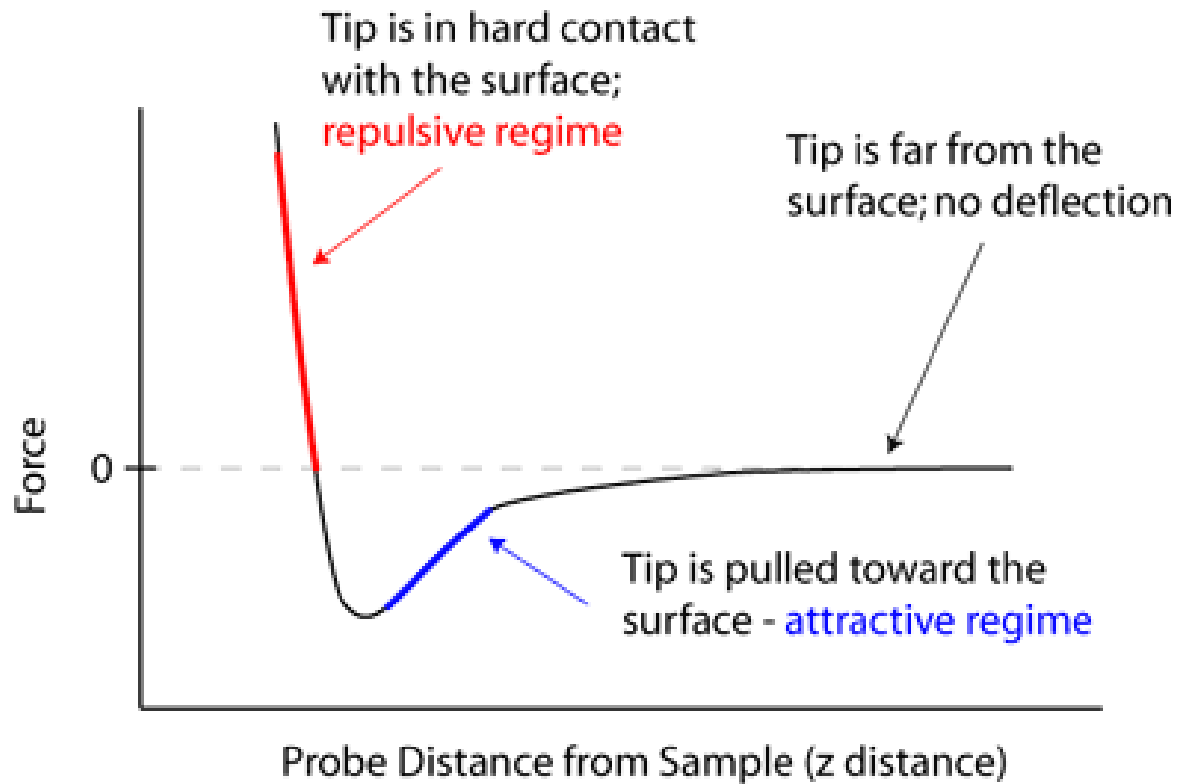
The cross-section shows a cantilever with a width $W=50$ and a length $L=160$. The tip is a thin tetrahedral shape with a height of 5.5 .

The top view shows a rectangular chip with dimensions 1.6 (length) and 3.4 (width). The cantilever is extended from the side edge of the chip, with a thickness of 0.3 .

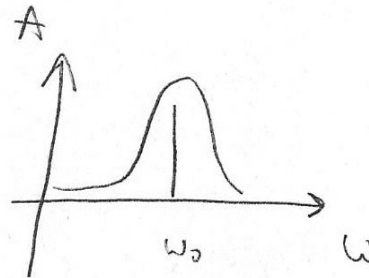
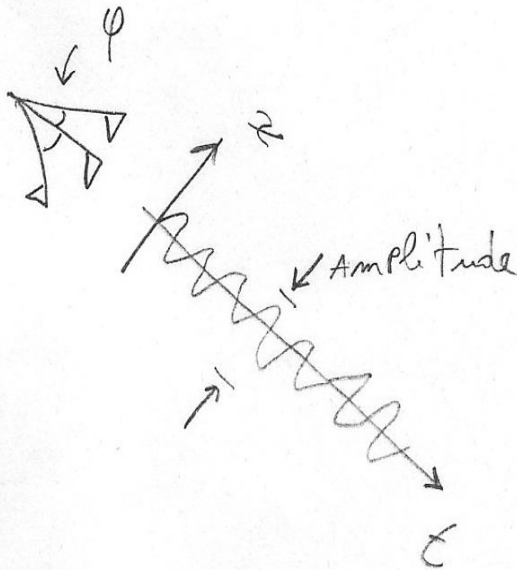
OMCL-AC160TS-
unit: μm

unit: mm

Operational Modes: CONTACT-MODE



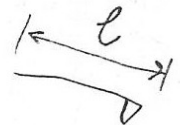
The cantilever vibration Physics:



$$\vec{F} = -k^* \Delta \phi$$

$$m \frac{d^2 \phi}{dt^2} = -k^* \phi$$

$$m \int \frac{d^2 \phi}{dt^2} = -k \int d\phi$$



$$dz = l d\varphi$$

$$m l \frac{d^2 \varphi}{dt^2} = -k d\varphi$$

$$m l \ddot{\varphi} = -k \varphi$$

$$m l \ddot{\varphi} + k \varphi = 0$$

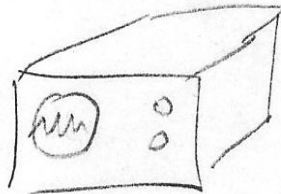
WAVE EQUATION \rightarrow SOLUTION

$$\ddot{\varphi} + \frac{k}{m l} \varphi = 0$$

$$\left. \begin{aligned} \varphi(t) &= A \sin(\omega_0 t) \\ \omega_0^2 &= \frac{k}{m l} \end{aligned} \right\} \star$$

How to measure the cantilever Force:

① OBSERVE ω_0 on oscilloscope



$$\Rightarrow \omega_0 \Rightarrow f_0 = \frac{\omega_0}{2\pi}$$

$$k^* = m l \omega_0^2 = m l 2\pi f_0$$

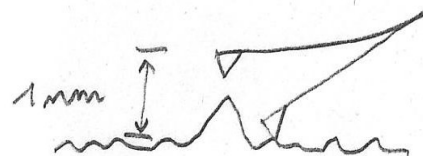
Suppose $\Delta z = 1 \text{ mm} = 10^{-9} \text{ [m]}$

$$\vec{F}_{\text{(over 1mm)}} = -k^* \frac{1}{l} \frac{10^{-9}}{l \text{ [m]}}$$

$$m = 0.01 \text{ [g]} \quad l = 0.001 \text{ [m]}$$

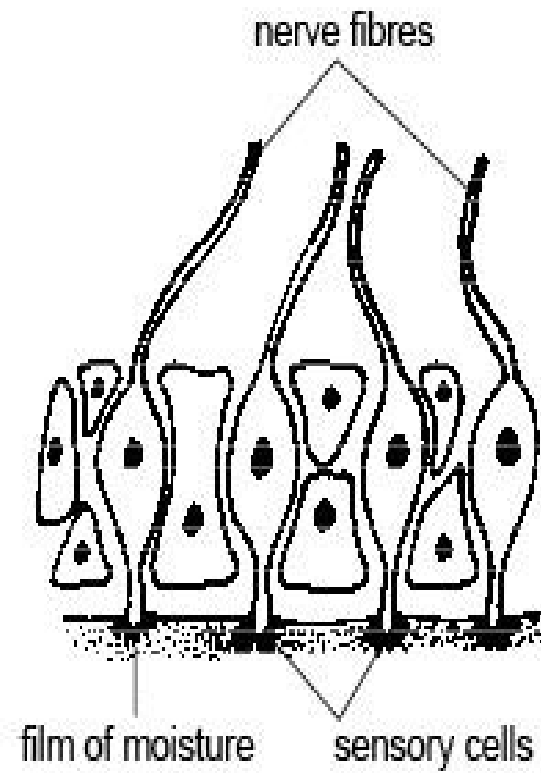
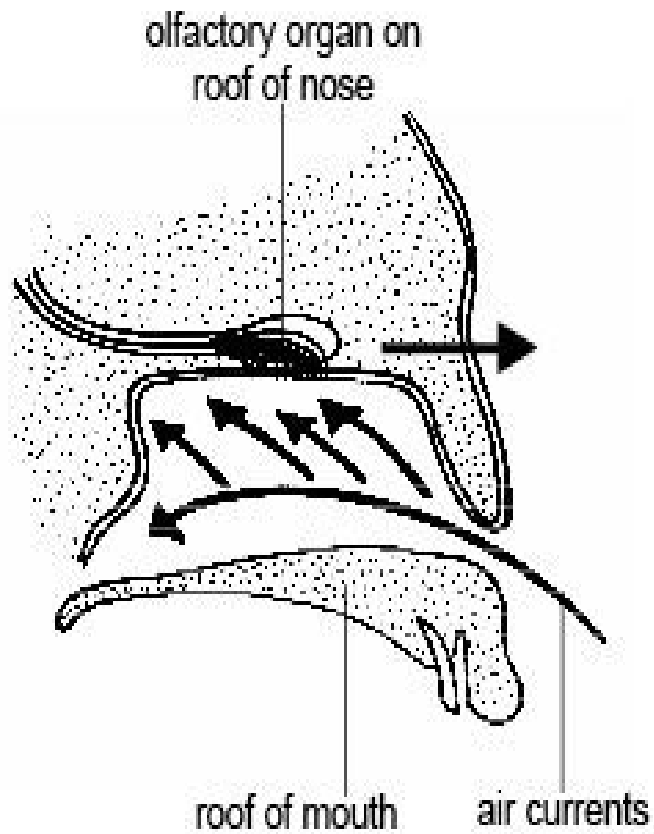
$$f = 50 \text{ kHz}$$

$$k^* = ? \quad F \Big|_{1\text{mm}} = ?$$

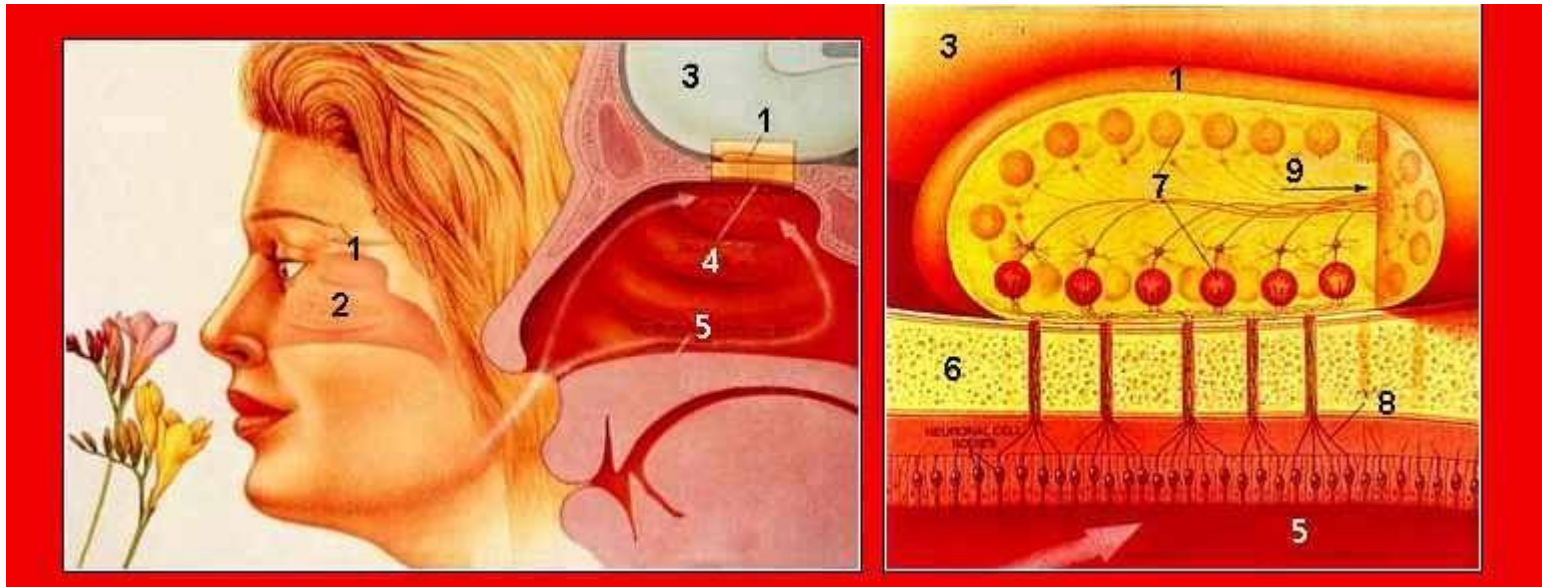


THE NOSE: the OLFACTORY sense (嗅覚、きゅうかく)

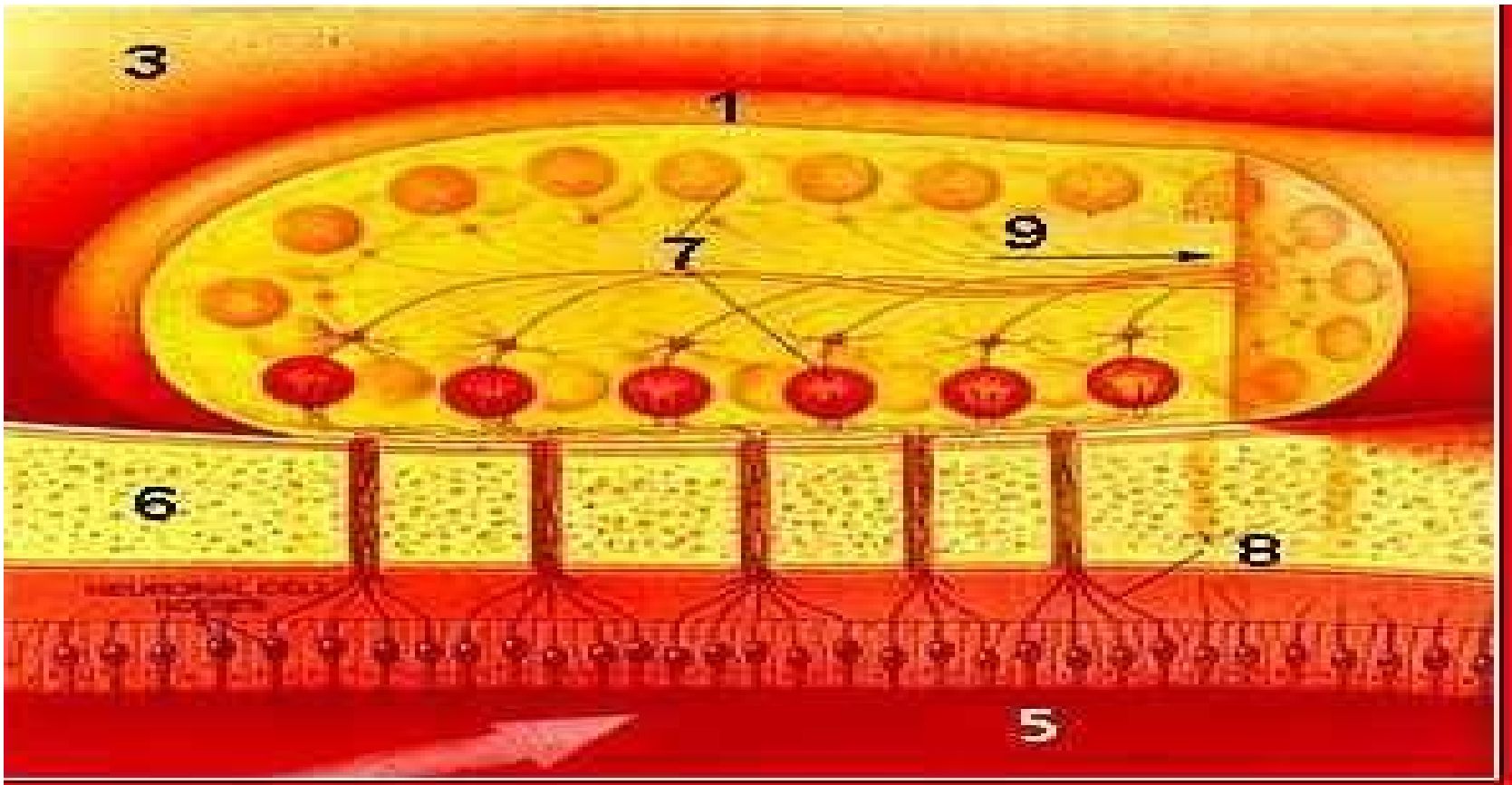




magnification of part of olfactory organ



The olfactory sensors are located in yellow pigmented areas on each side of the inner nose. These areas are about 2.5 cm^2 in area each, and contain chemoreceptors, which are nerve cells responding to certain chemicals that are carried to the sensors as gases. The detailed functioning of these cells does not appear to be known.

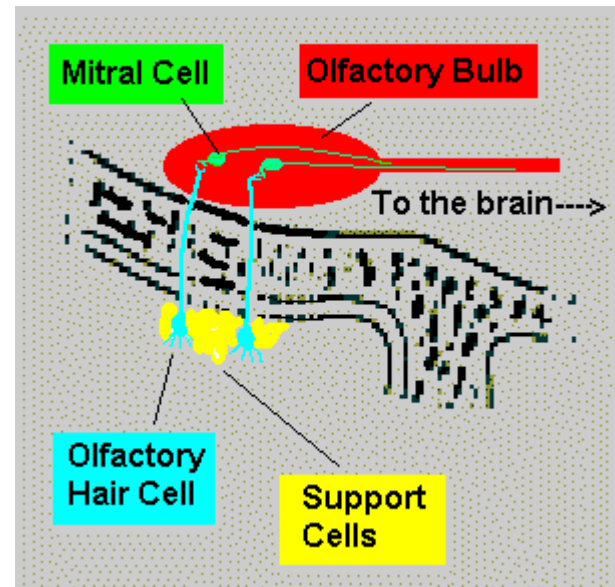
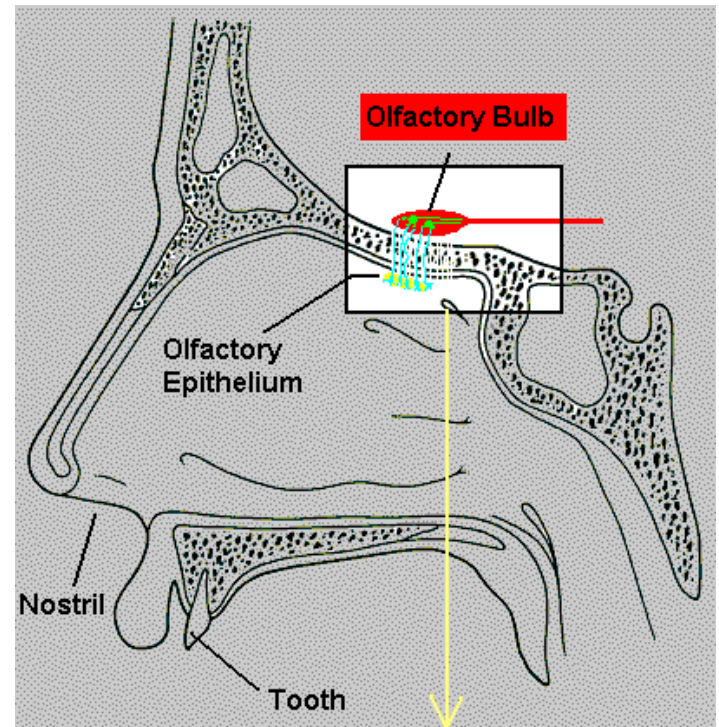


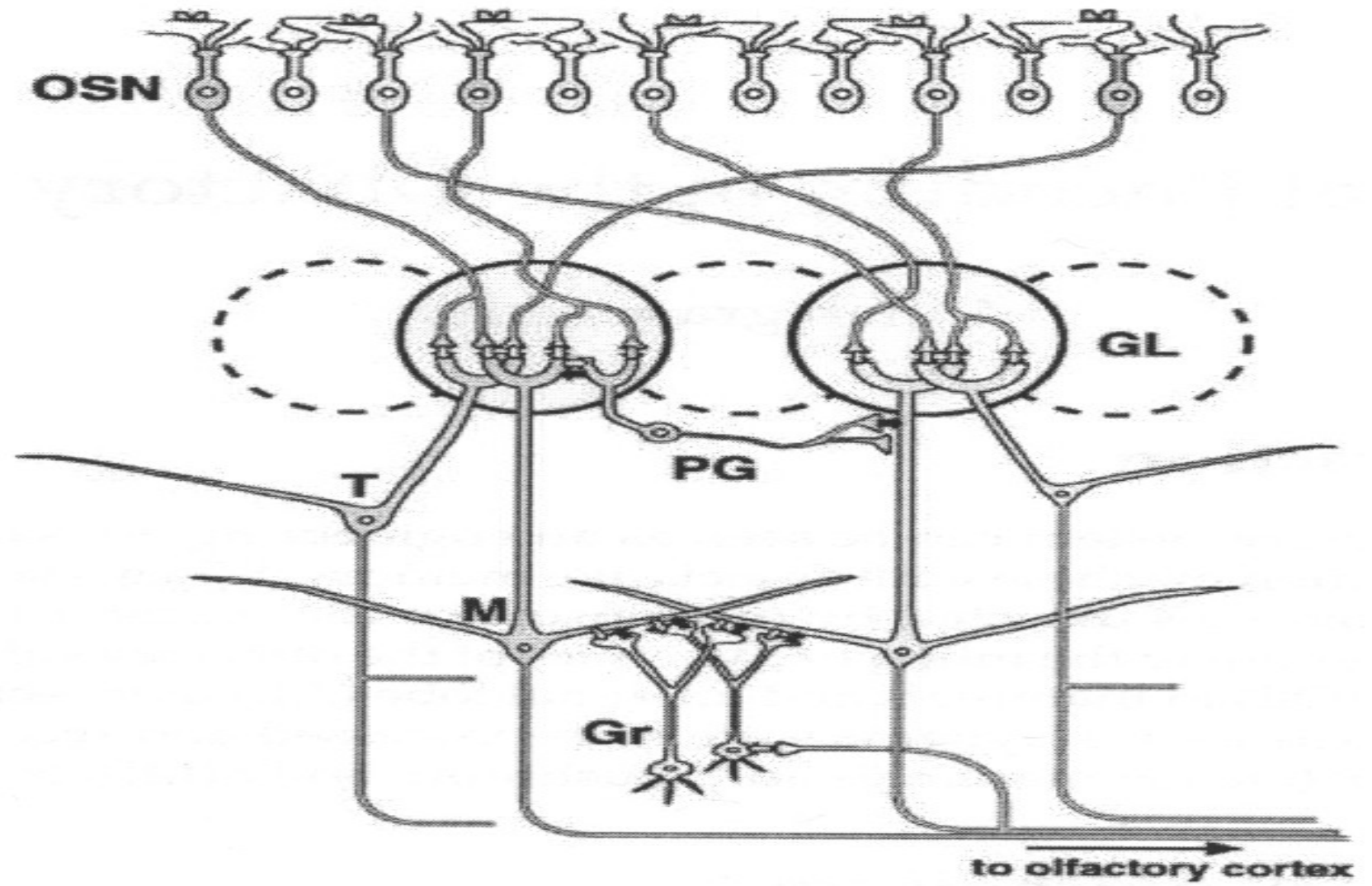
The glomeruli, each receiving signals from some 26 000 receptors. The olfactory bulbs on either side are cross-connected. Finally nerve fibres reach the olfactory areas in the anterior lobes of the brain.

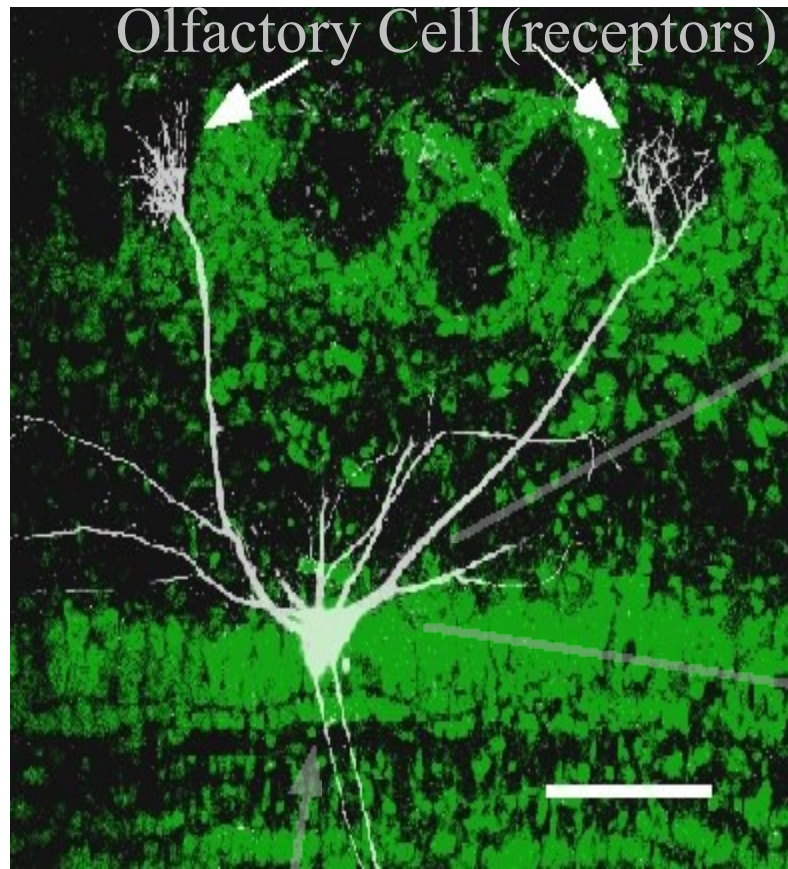
- The olfactory sense is some **10000** times as sensitive as taste, and is **primarily** responsible for the flavours of food.

- The types of olfactory sensations are 6:

fruity, **flowery**, **resinous**, **spicy**,
foul (**rotten**), and **burned**.

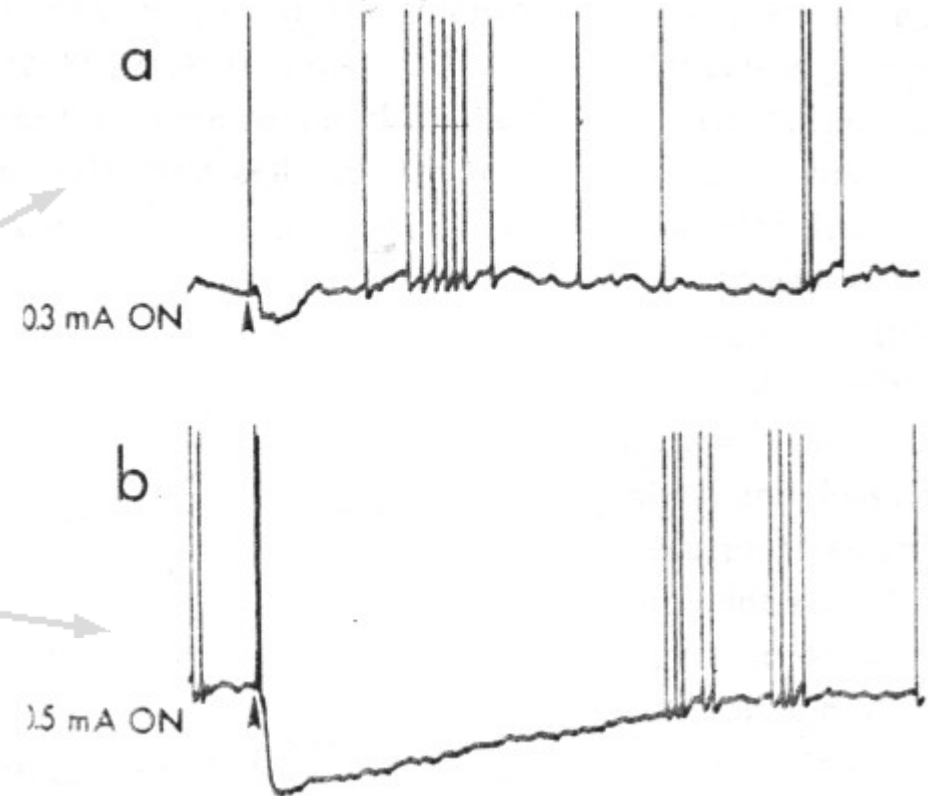




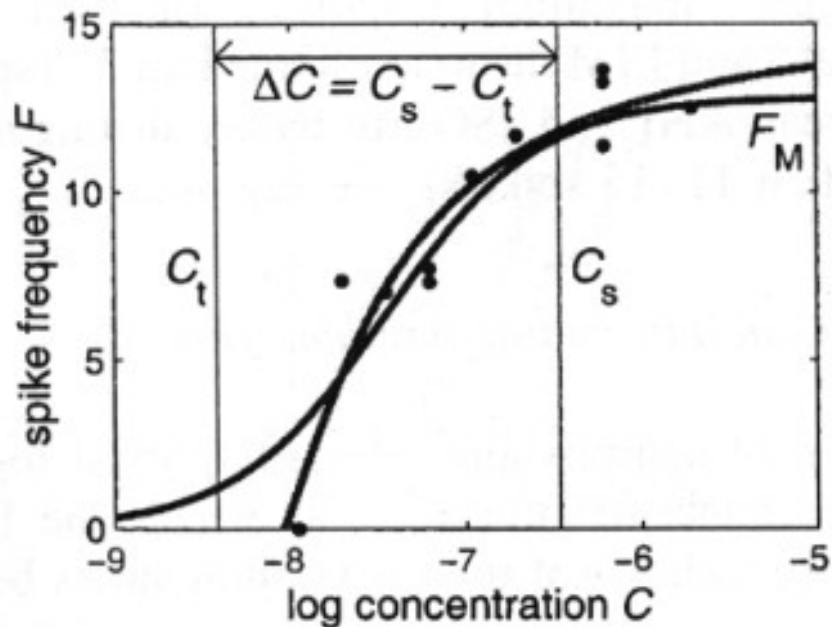


Mitral Cell

Signal from Mitral Cells

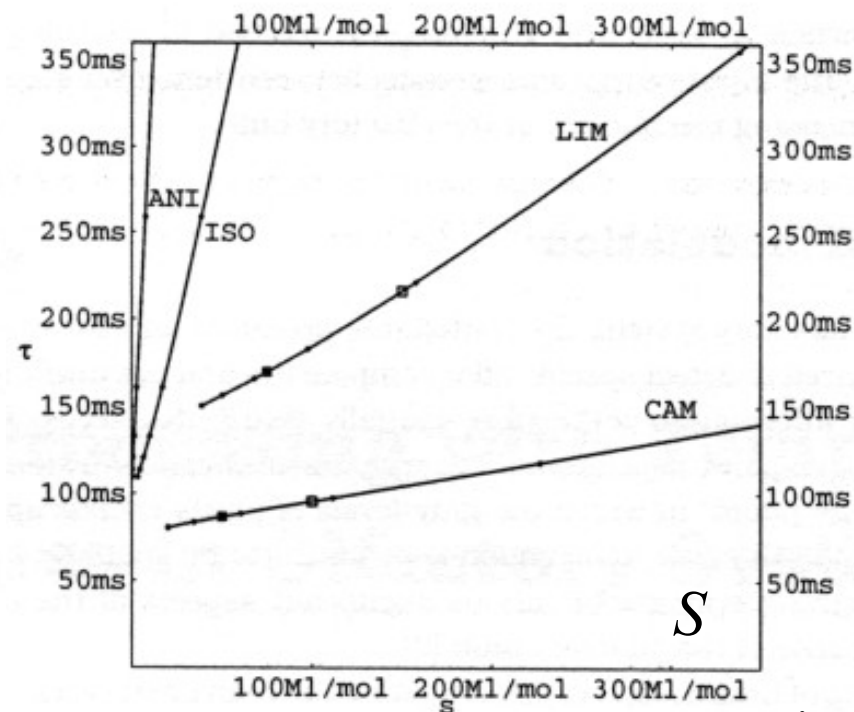


スパイク周波数



香科密度

スパイクの時間間隔



香科密度

S =sparsity

$$\tau = \tau_0 + Gs$$

$$\tau = \tau_0 + Gs$$

Gは gain といいます。

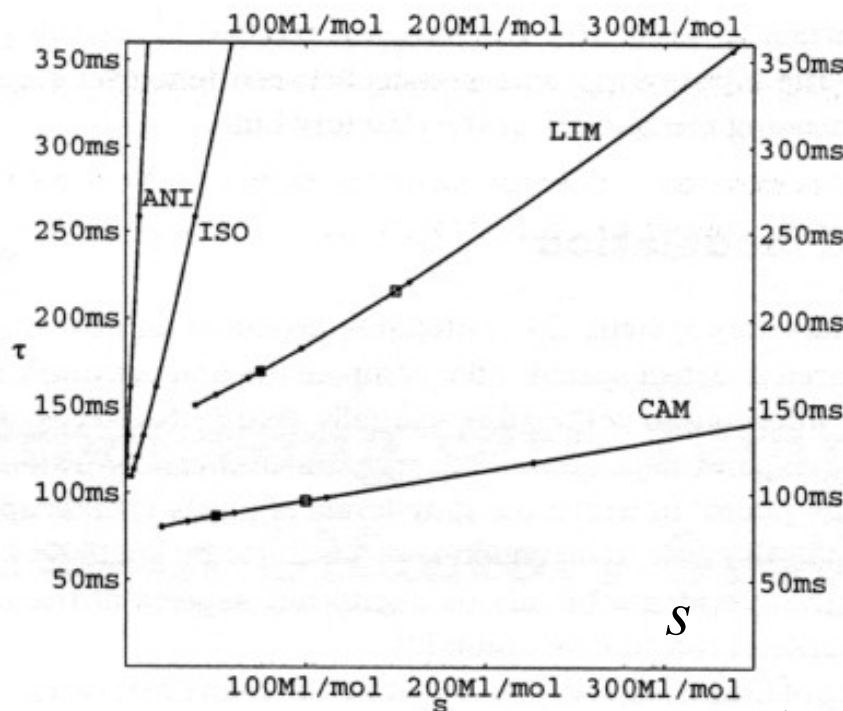
香料によってGは違います。

例： $G_{\text{camphor}} = 1.0$

$G_{\text{lemon}} = 2.5$

$G_{\text{anisole}} = 20$

スパイクの時間間隔

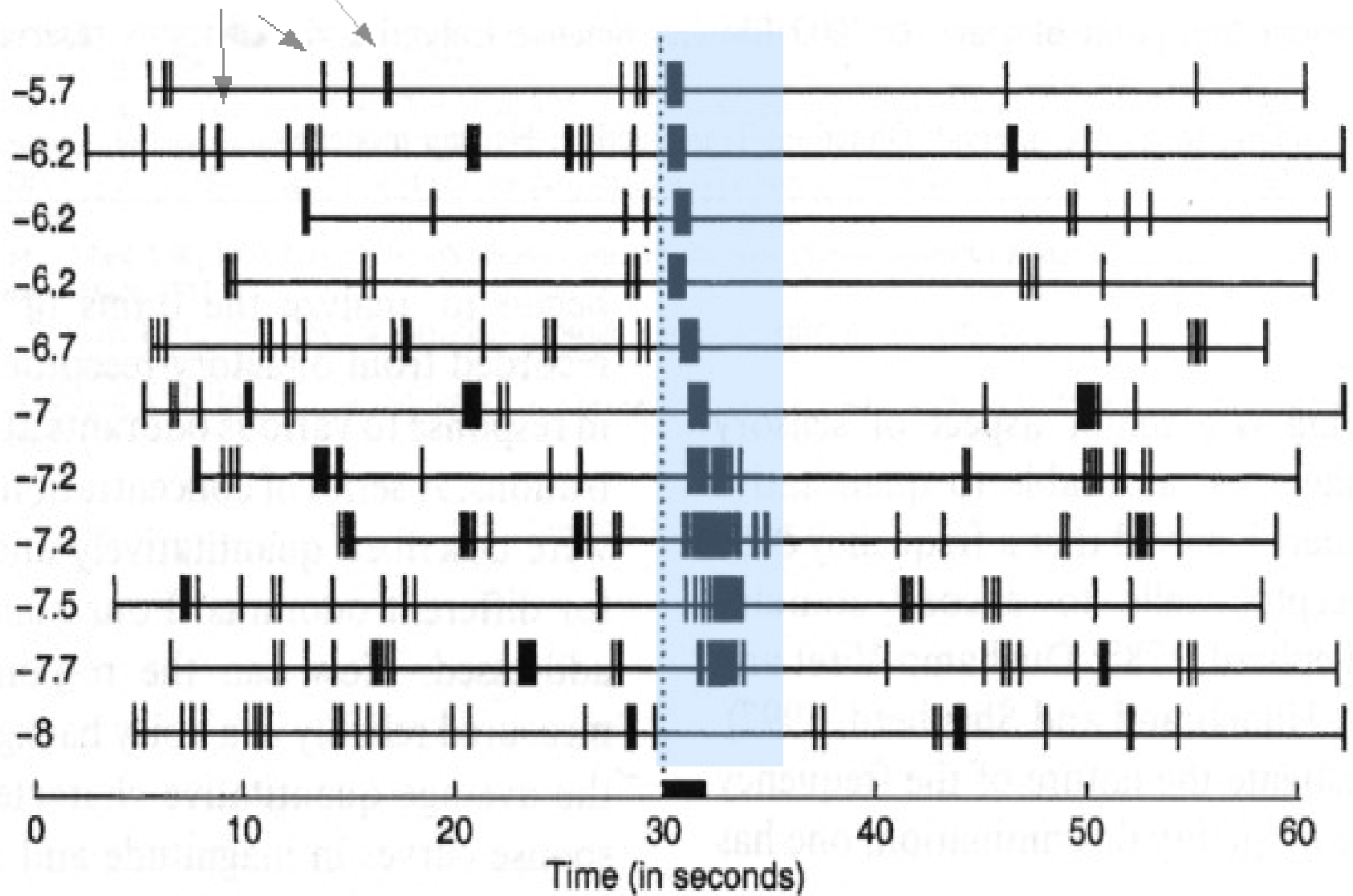


香料密度

$s = \text{sparsity}$

Limonene 香科で実験

スパイク

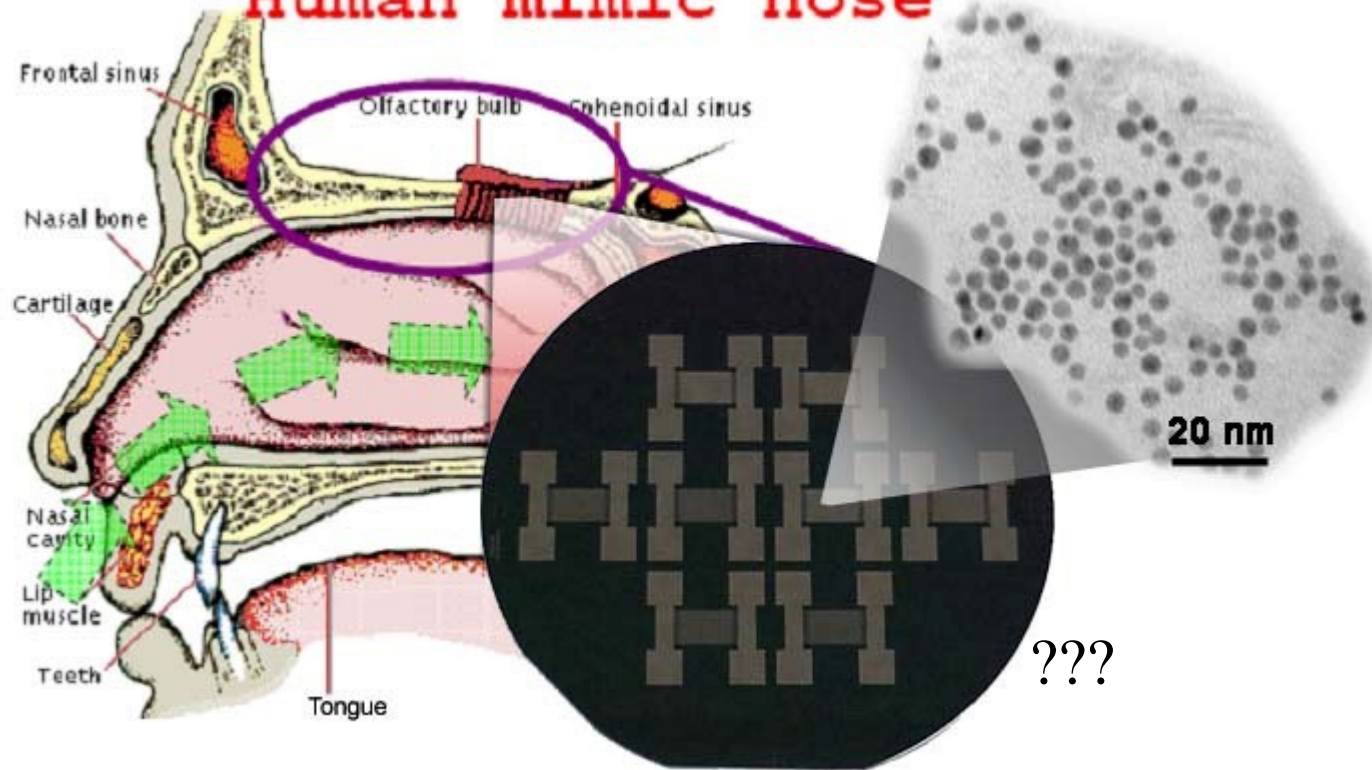


人工嗅覚

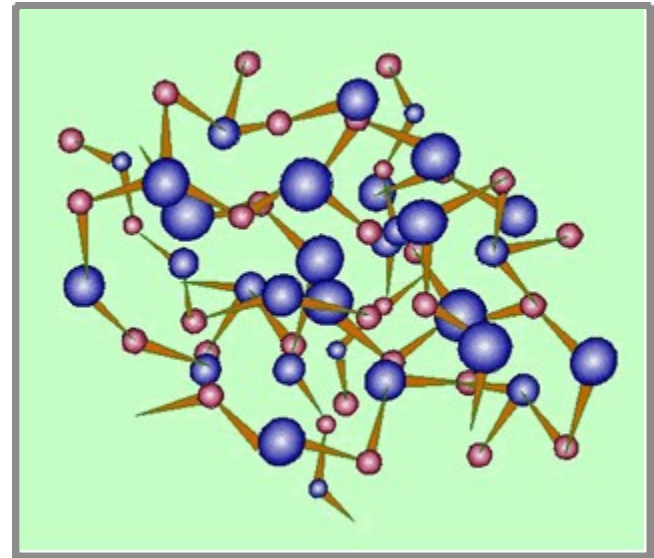
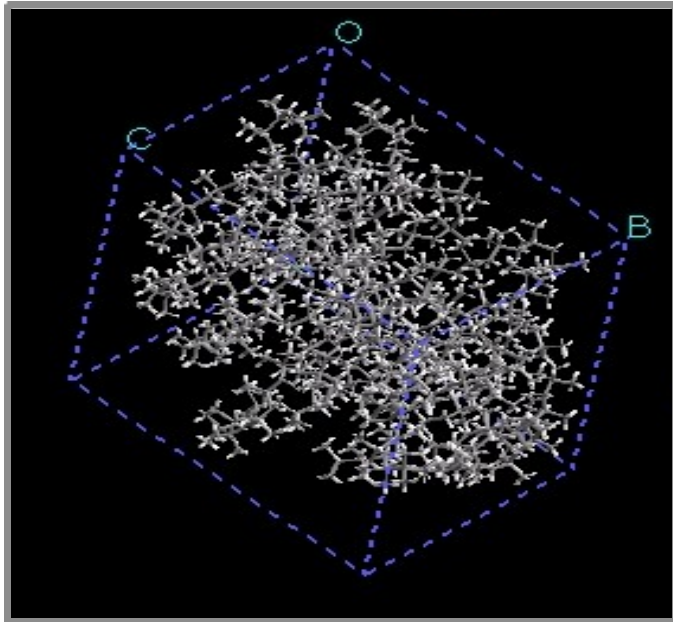


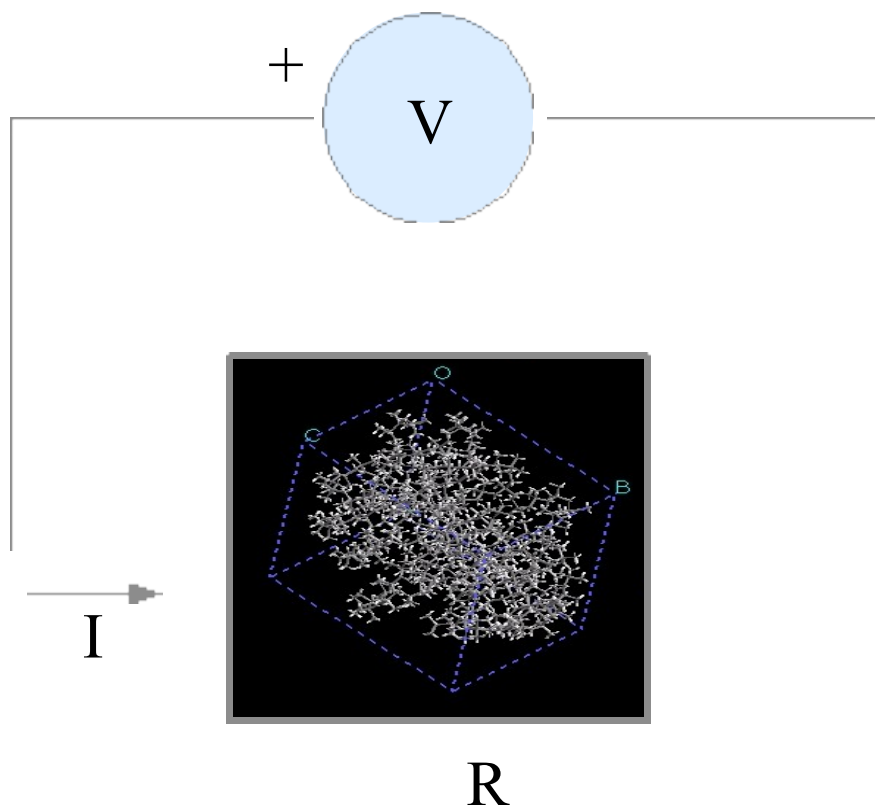
JPL 人工嗅覚デバイス

Human mimic nose



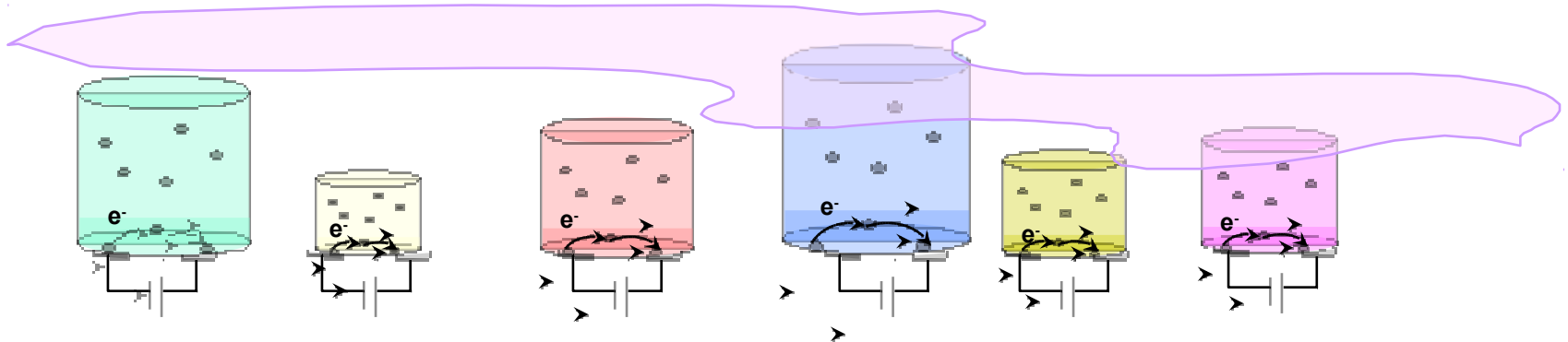
Polymers complex structure





THE ELECTRONIC NOSE SMELLS SOMETHING

Each polymer changes its size, and therefore its resistance, by a different amount, making a pattern of the change



If a different compound had caused the air to change, the pattern of the polymer films' change would have been different:

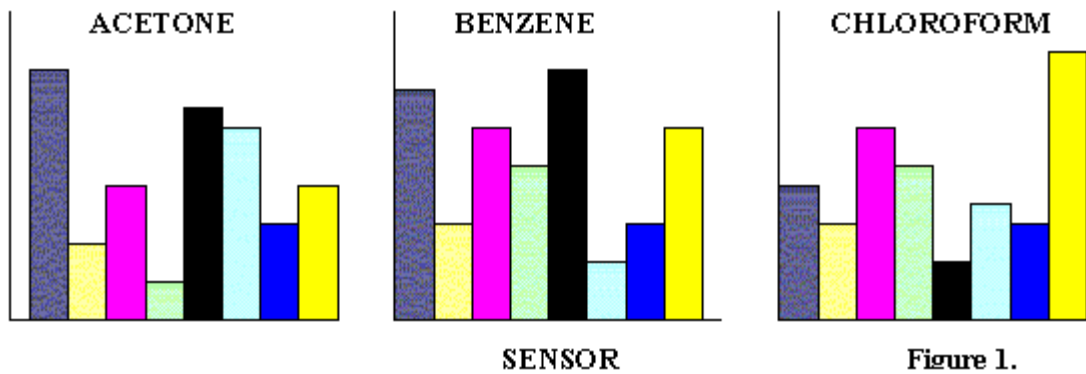
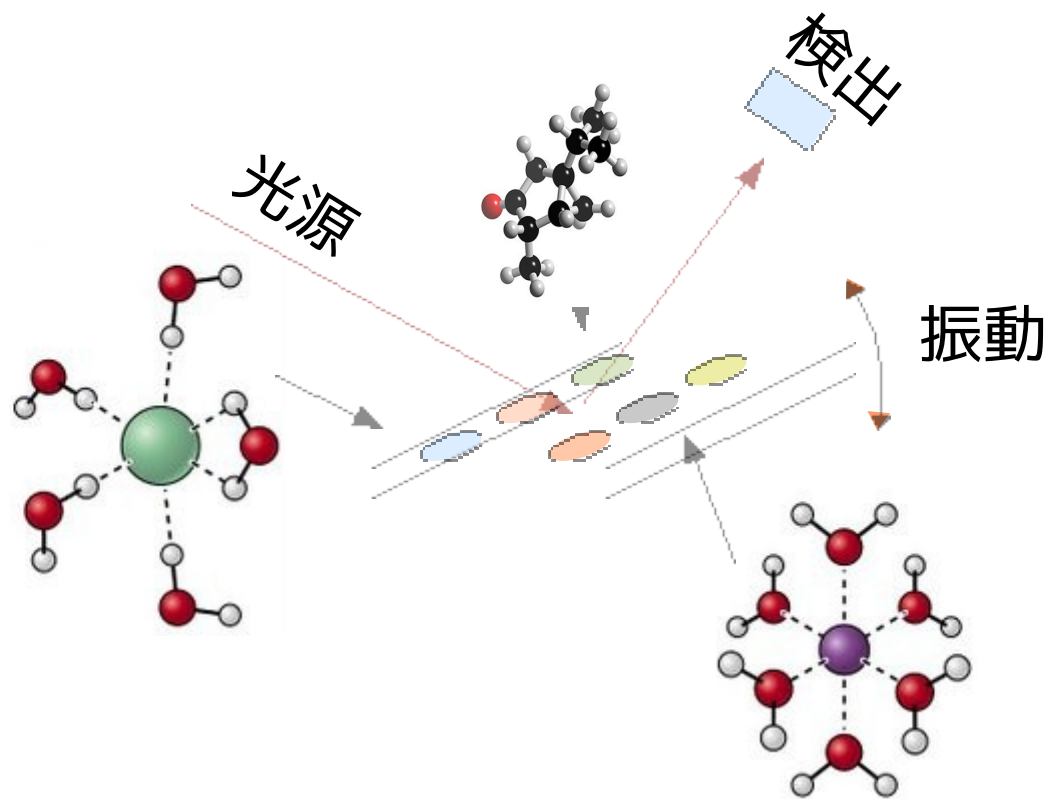


Figure 1.

AFM NOSE



結合する分子によって振動のパターンが異なる。