

国際総合科学・基盤科学

物理博士 ミケレット・ルジェロ

物質機能科学**IIb**

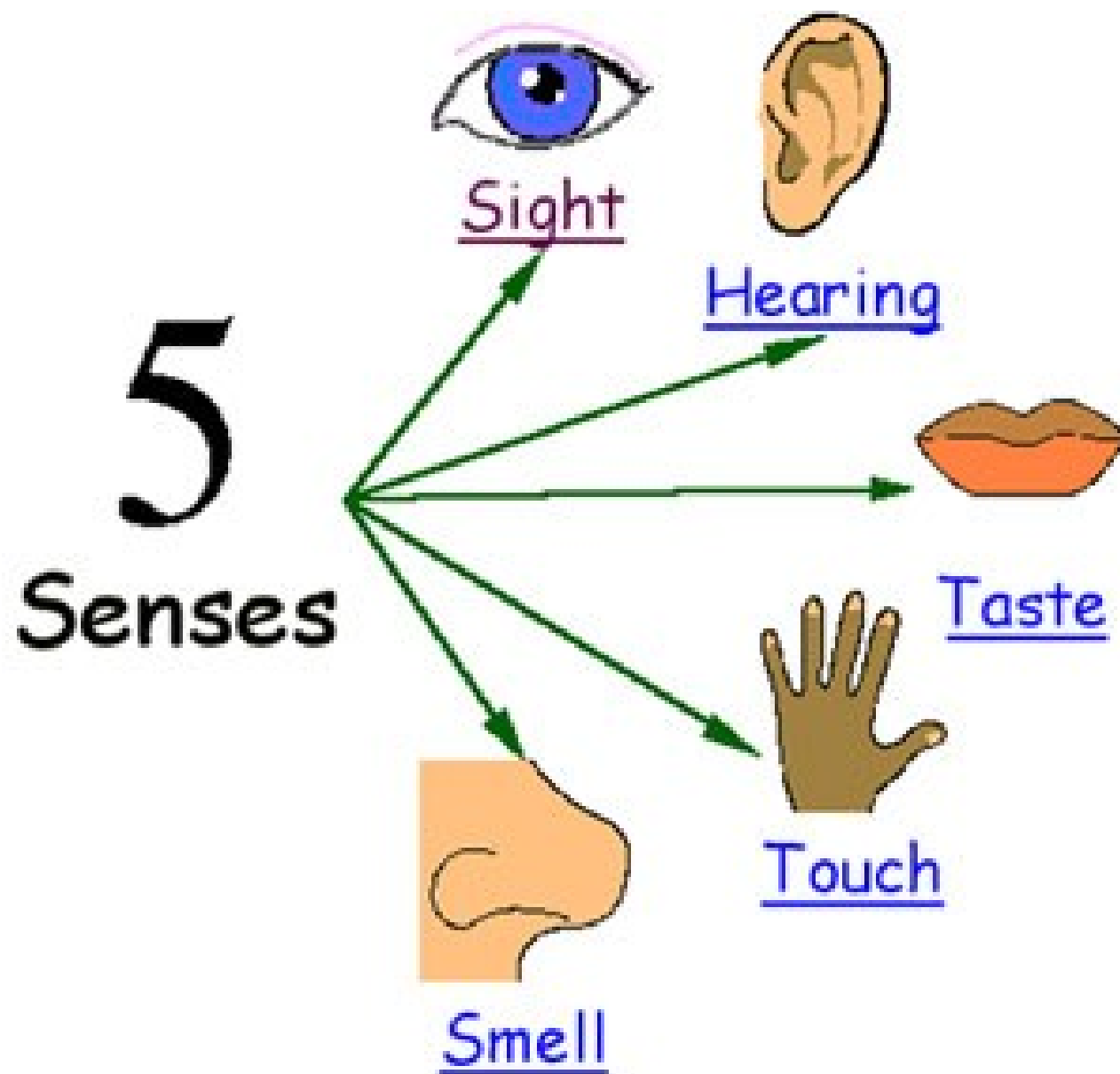
e-mail:ruggero@yokohama-cu.ac.jp

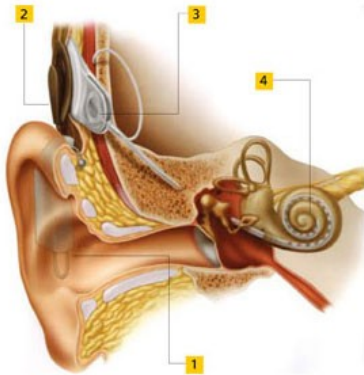
(8)

後期 2 0 0 9 年

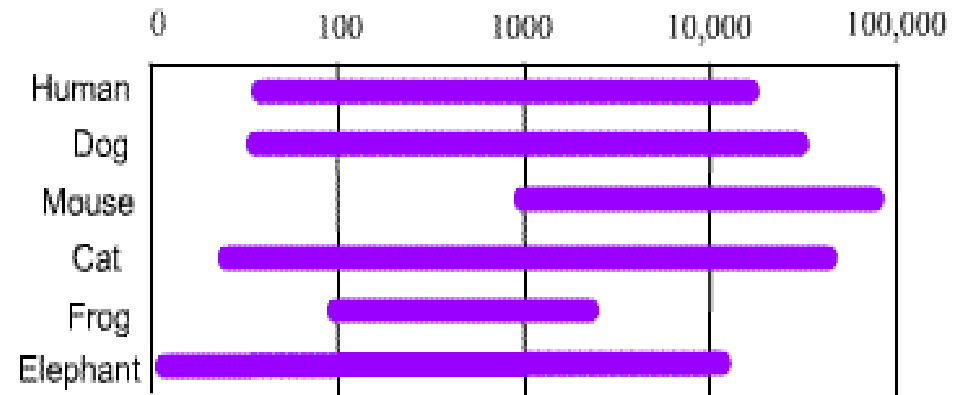
THE EAR: the HEARING sense (聴覚、ちょうかく)







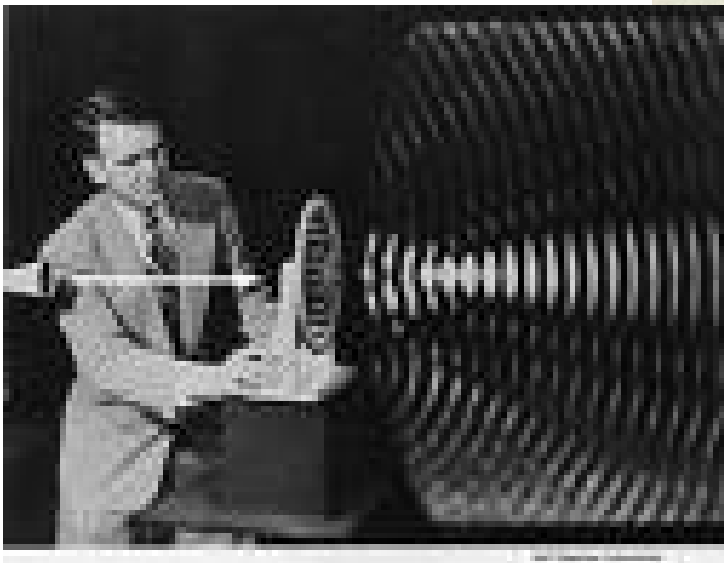
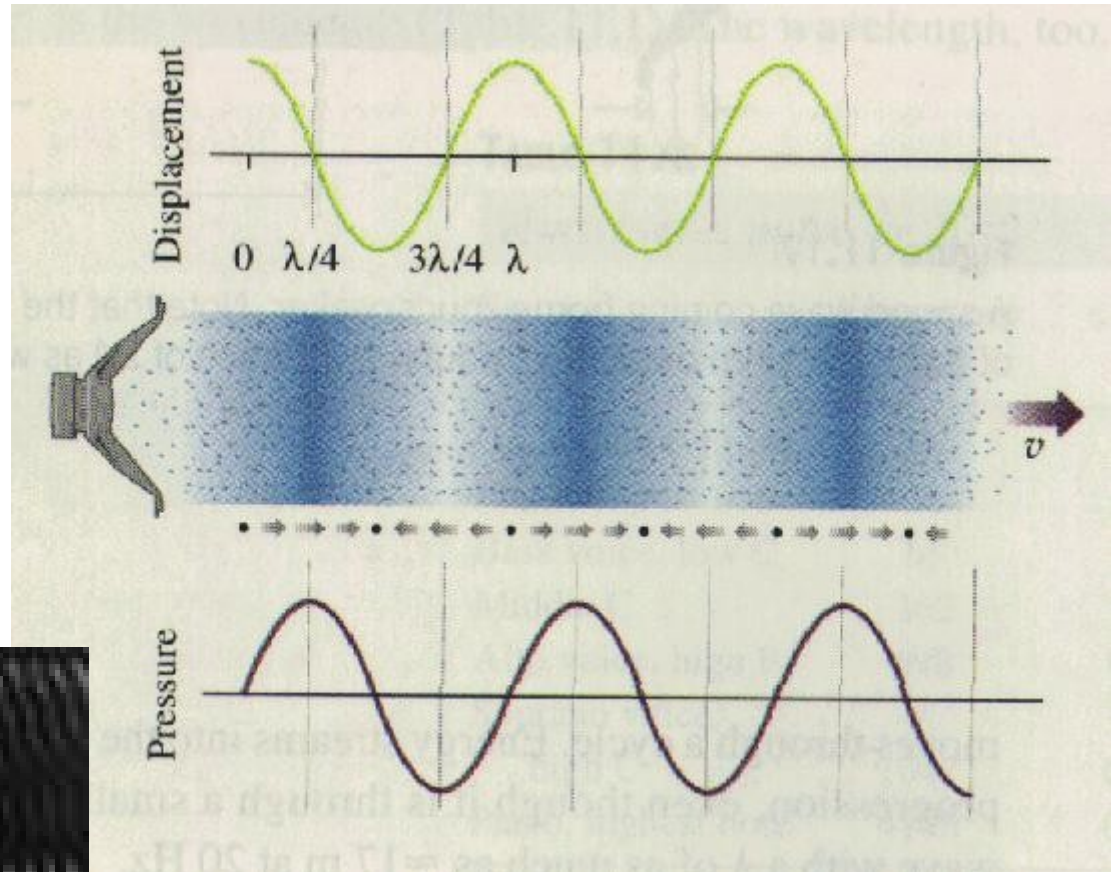
Frequency

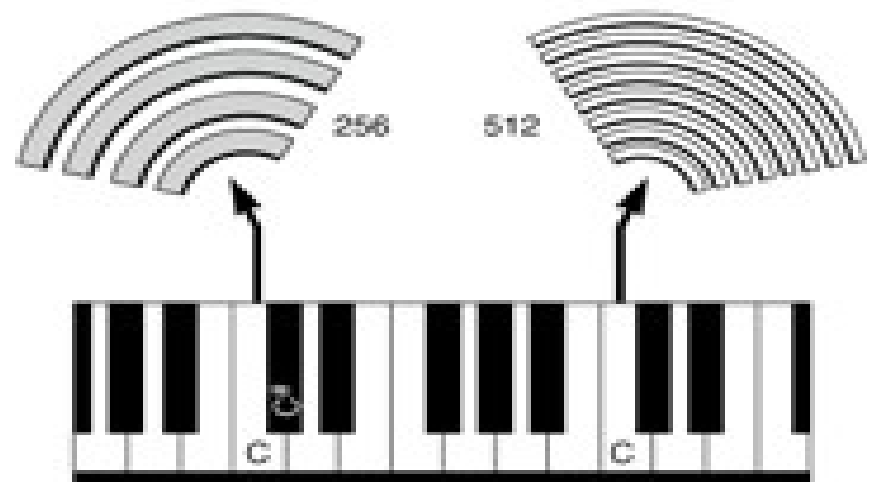
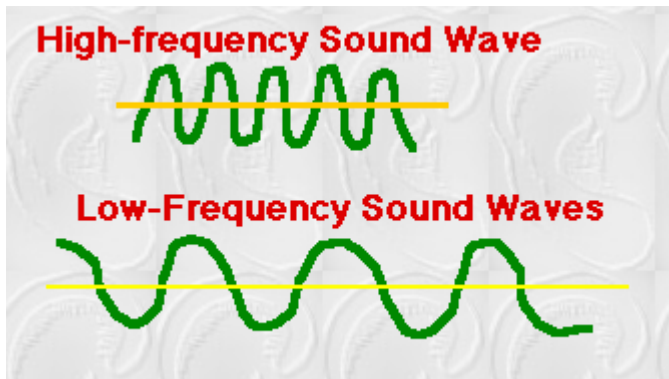
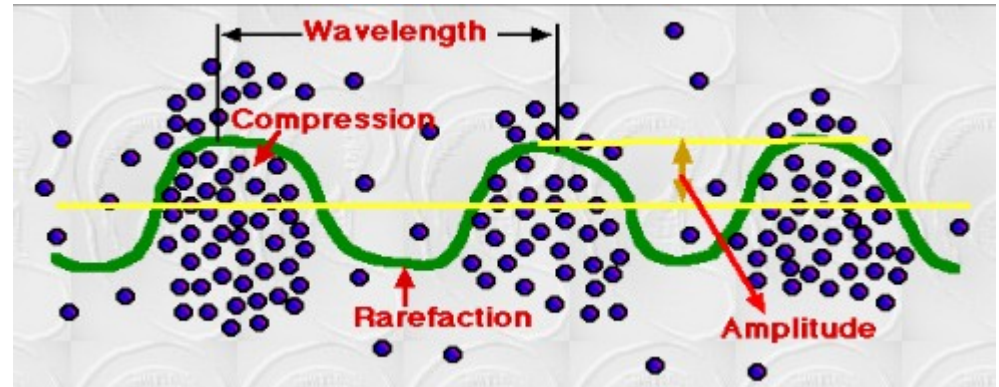
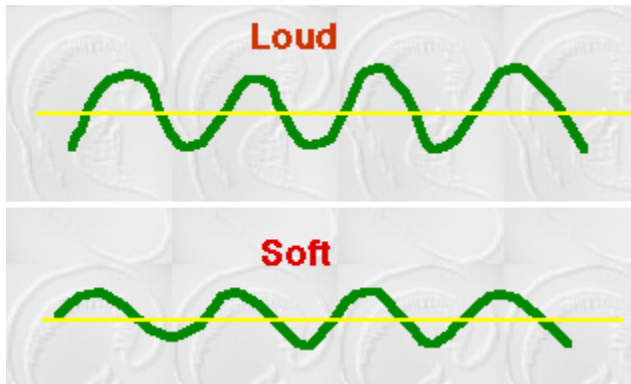


Noise	Decibels
Whisper	20
Normal Talking	50-60
Car Traffic	70
Alarm Clock	80
Lawn Mower	95
Rock Concert	100
Jackhammer	115
Jet Engine	130
Gun Shot	140

Amplitude

The sound it is a PRESSURE WAVE





The sound it is a PRESSURE WAVE

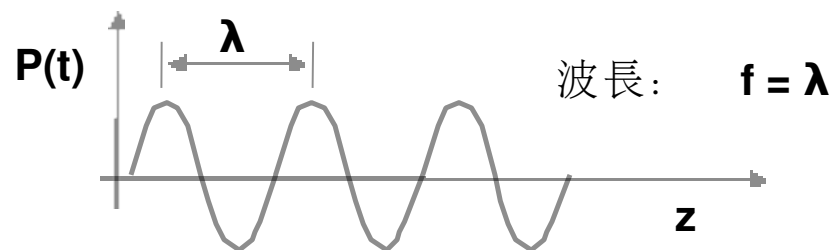
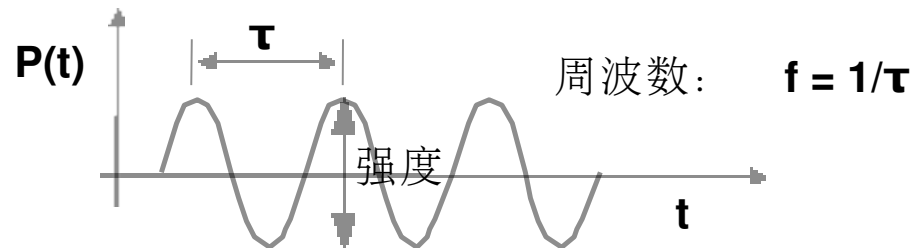
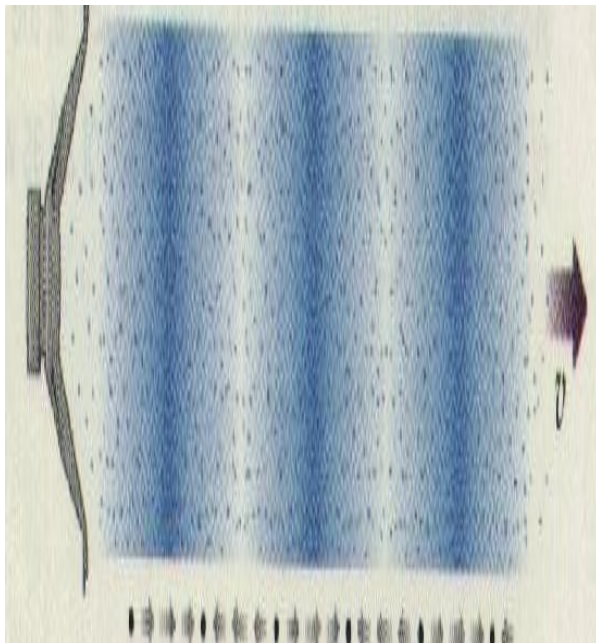
空気の圧力

f=Frequency
 λ =Wavelength

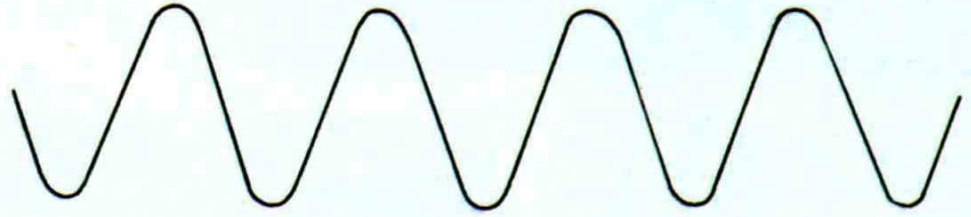
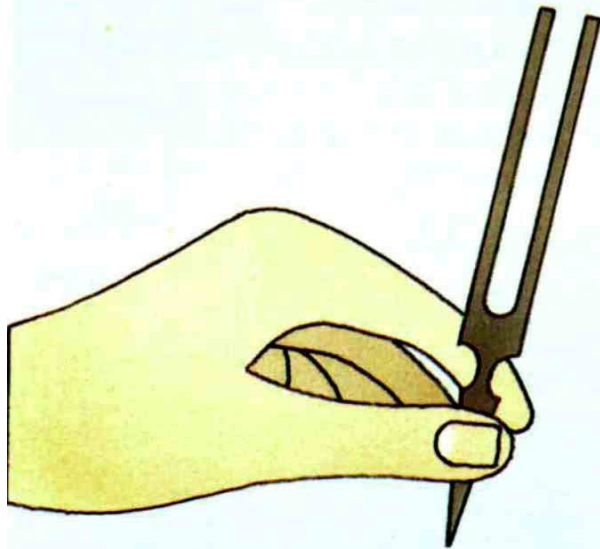
$$P(t) = P_o \sin(\omega t + kx)$$

$$\omega = 2\pi/\tau = 2\pi f$$

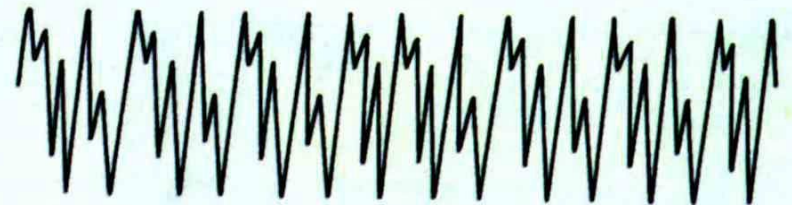
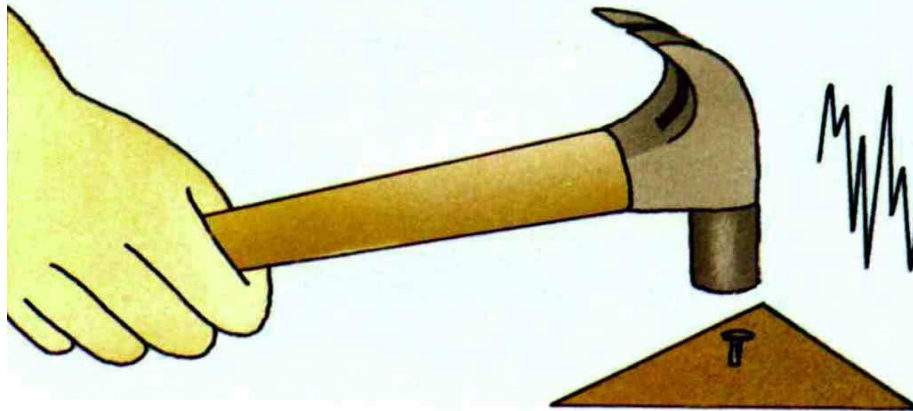
$$k = 2\pi/\lambda$$



PURE SOUND:



NOISE:

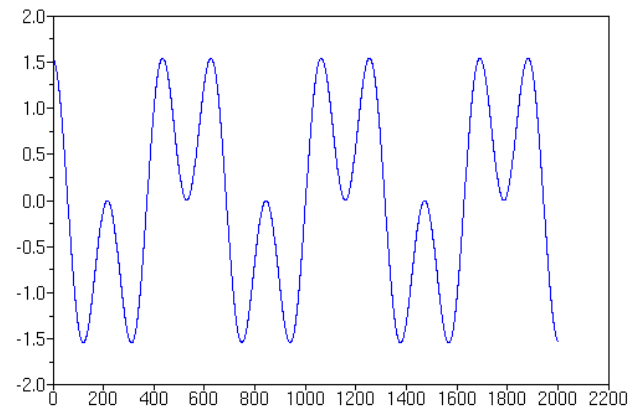
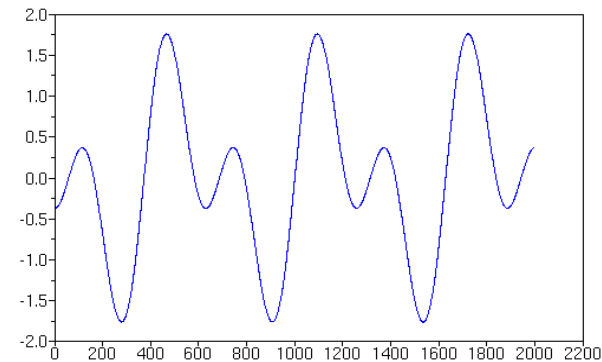
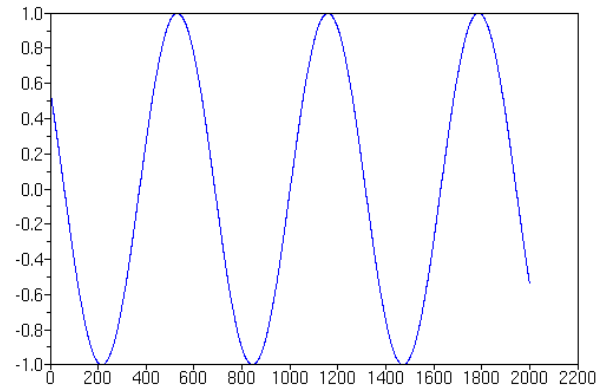


The sound SPECTRUM

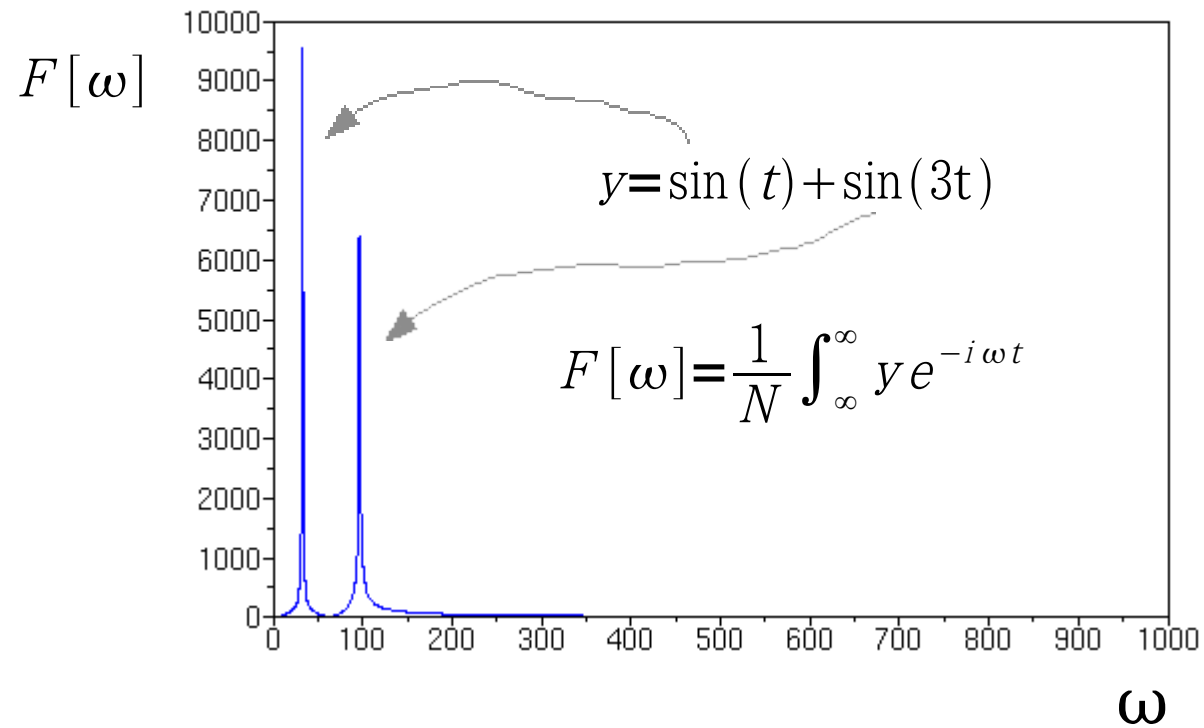
$$y = \sin(t)$$

$$y = \sin(t) + \sin(2t)$$

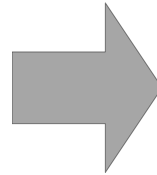
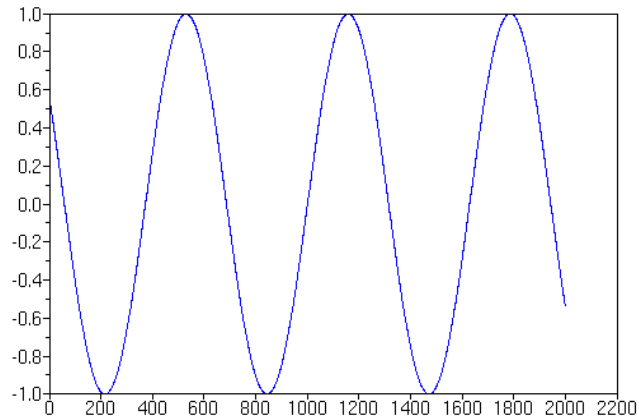
$$y = \sin(t) + \sin(3t)$$



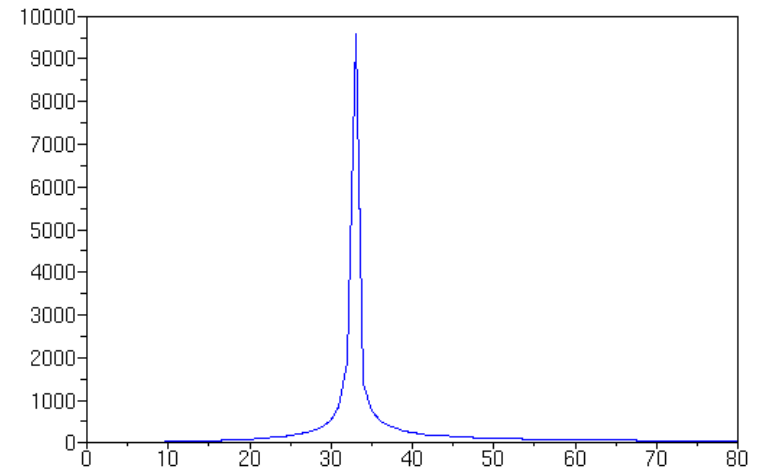
The FOURIER transformation



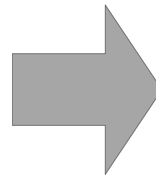
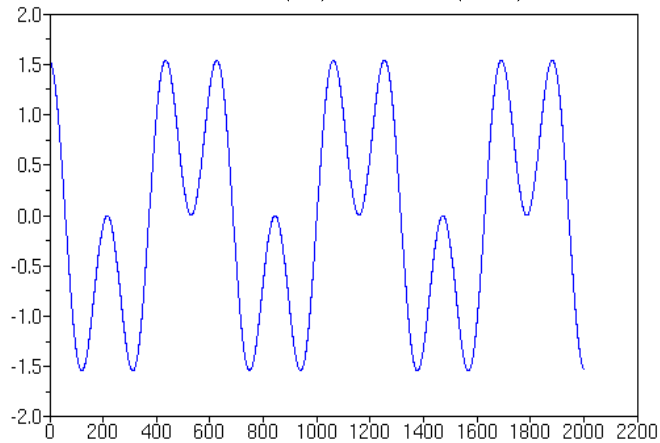
$$y = \sin(t)$$



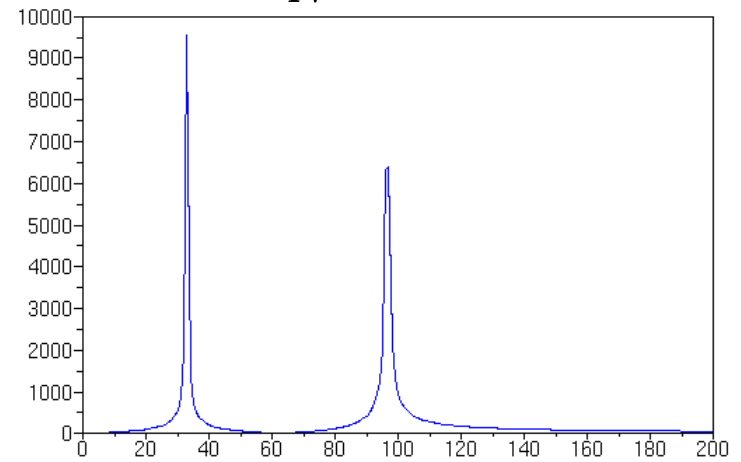
$$F[\omega] = \frac{1}{N} \int_{-\infty}^{\infty} y e^{-i\omega t} dt$$



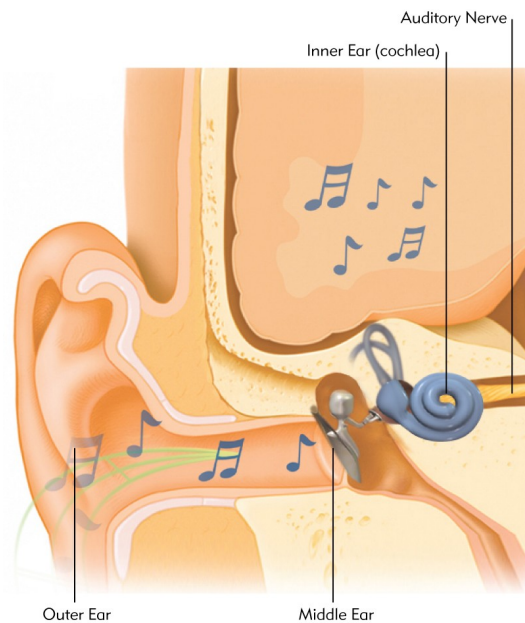
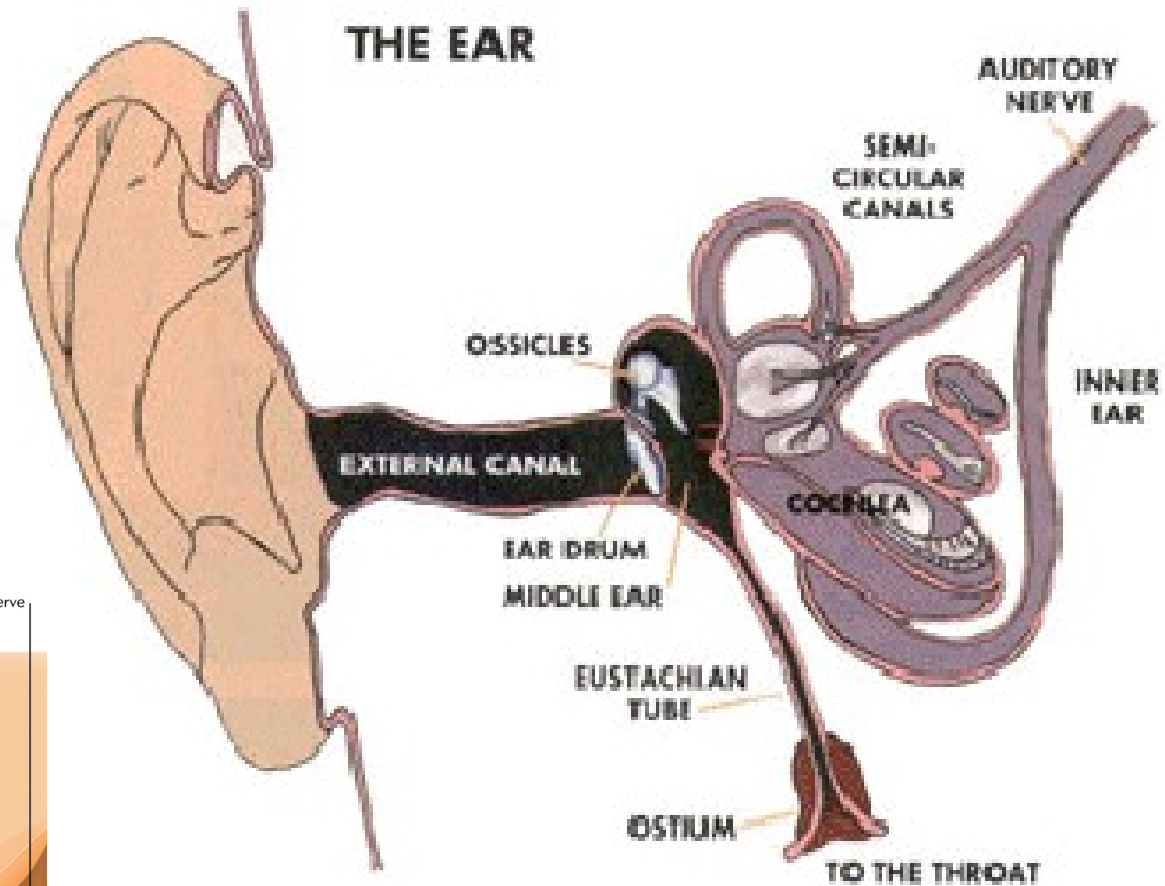
$$y = \sin(t) + \sin(3t)$$



$$F[\omega] = \frac{1}{N} \int_{-\infty}^{\infty} y e^{-i\omega t} dt$$



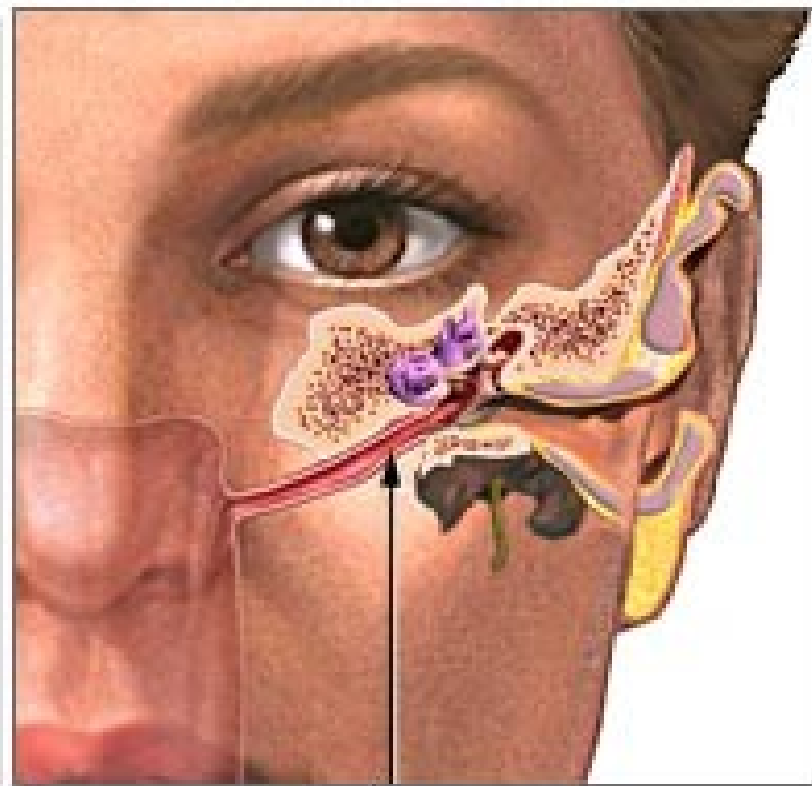
Inner Ear
Middle Ear
Outer Ear



Infant



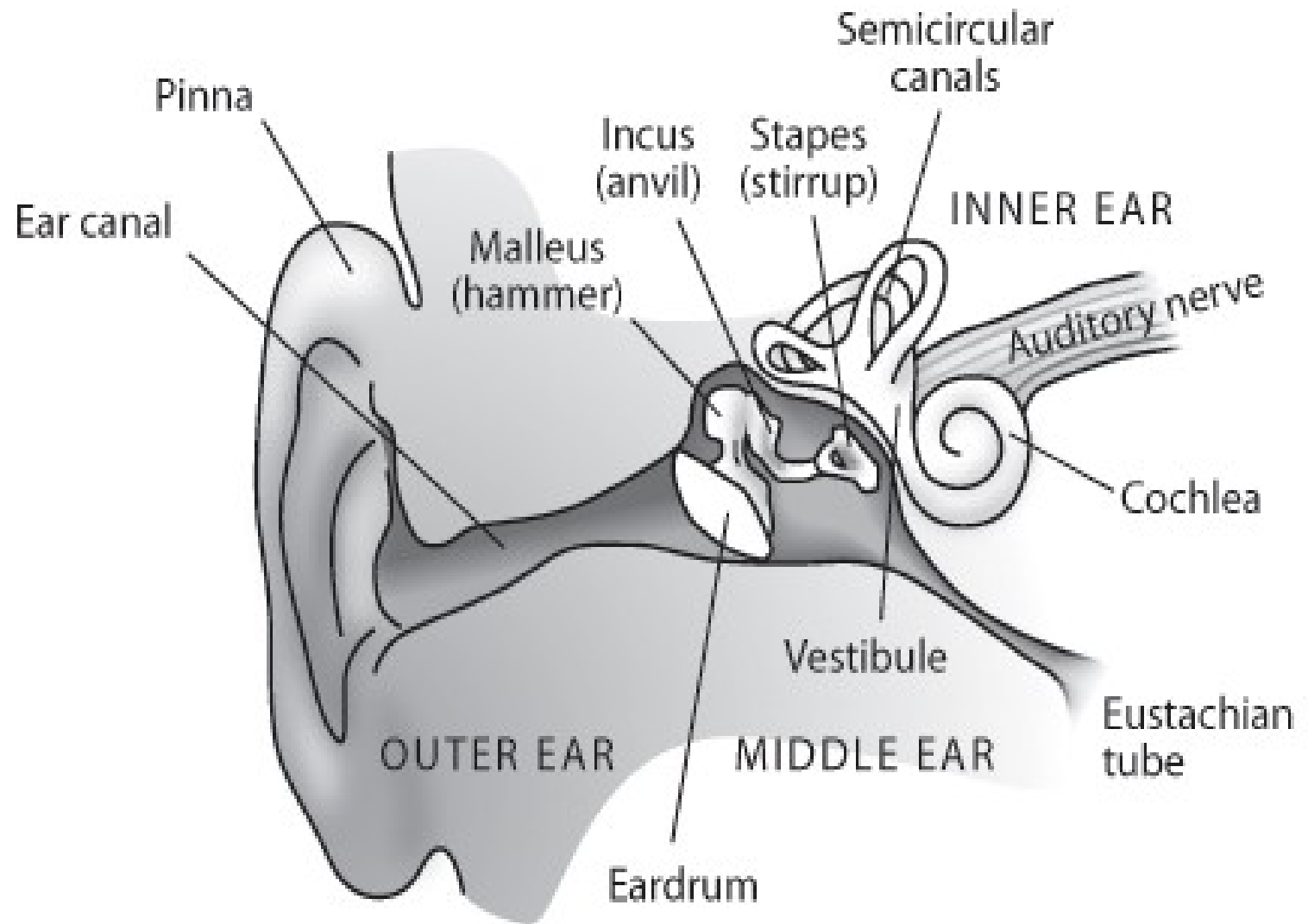
Adult



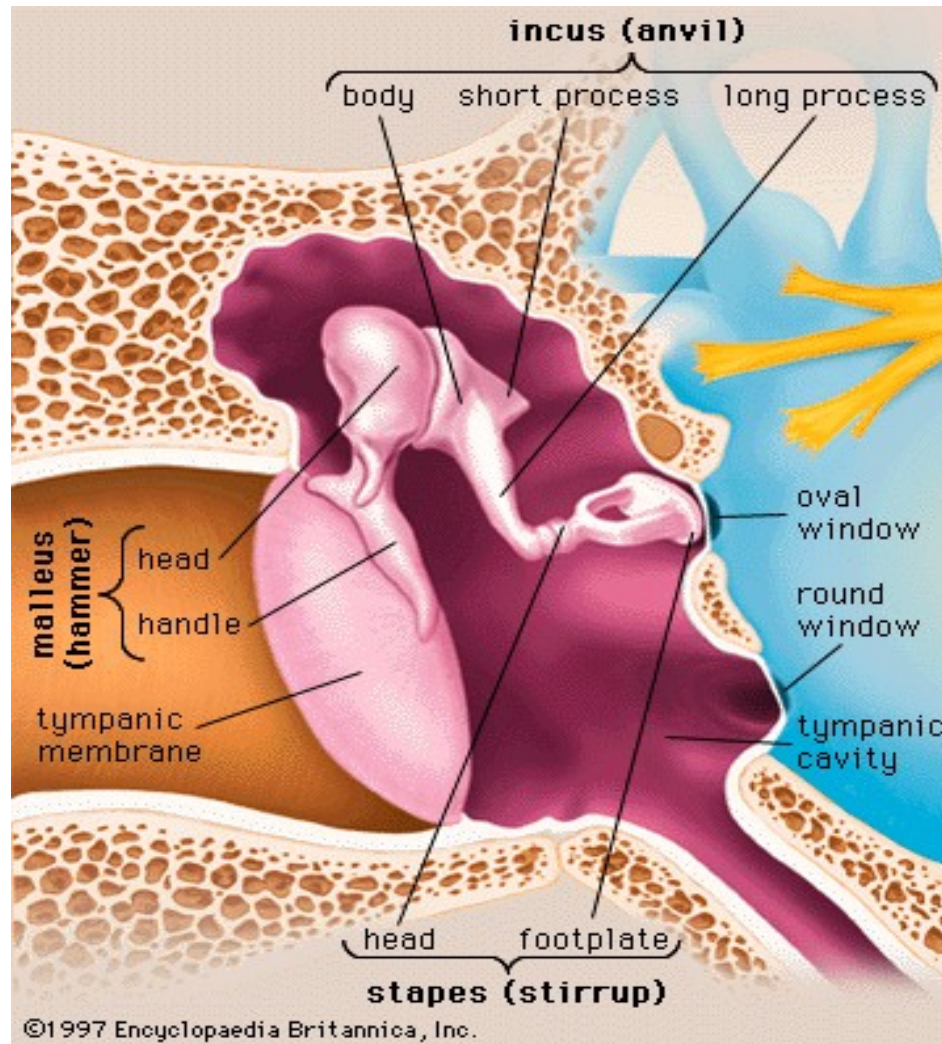
Eustachian tube



Inner Ear



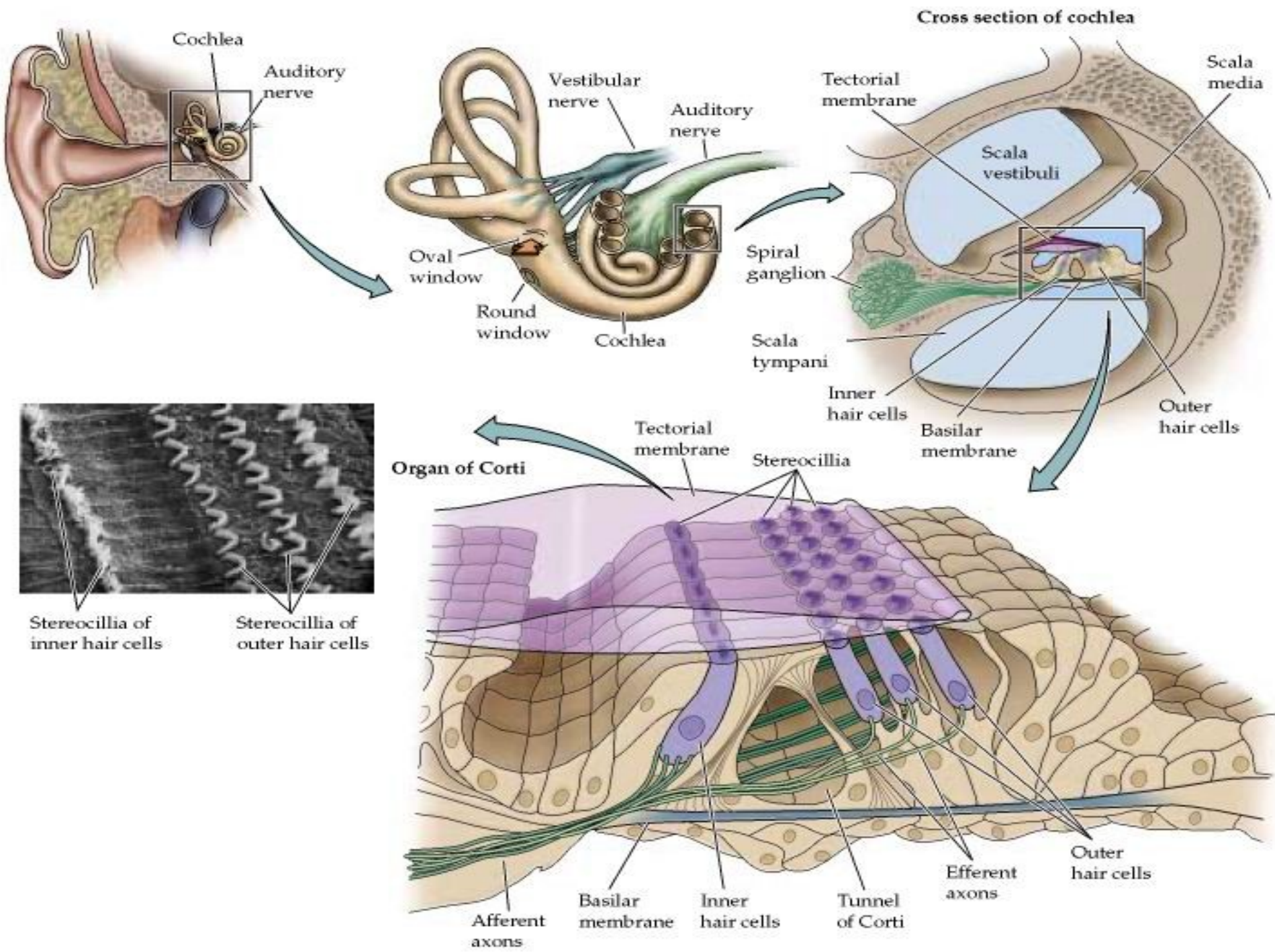
Middle Ear

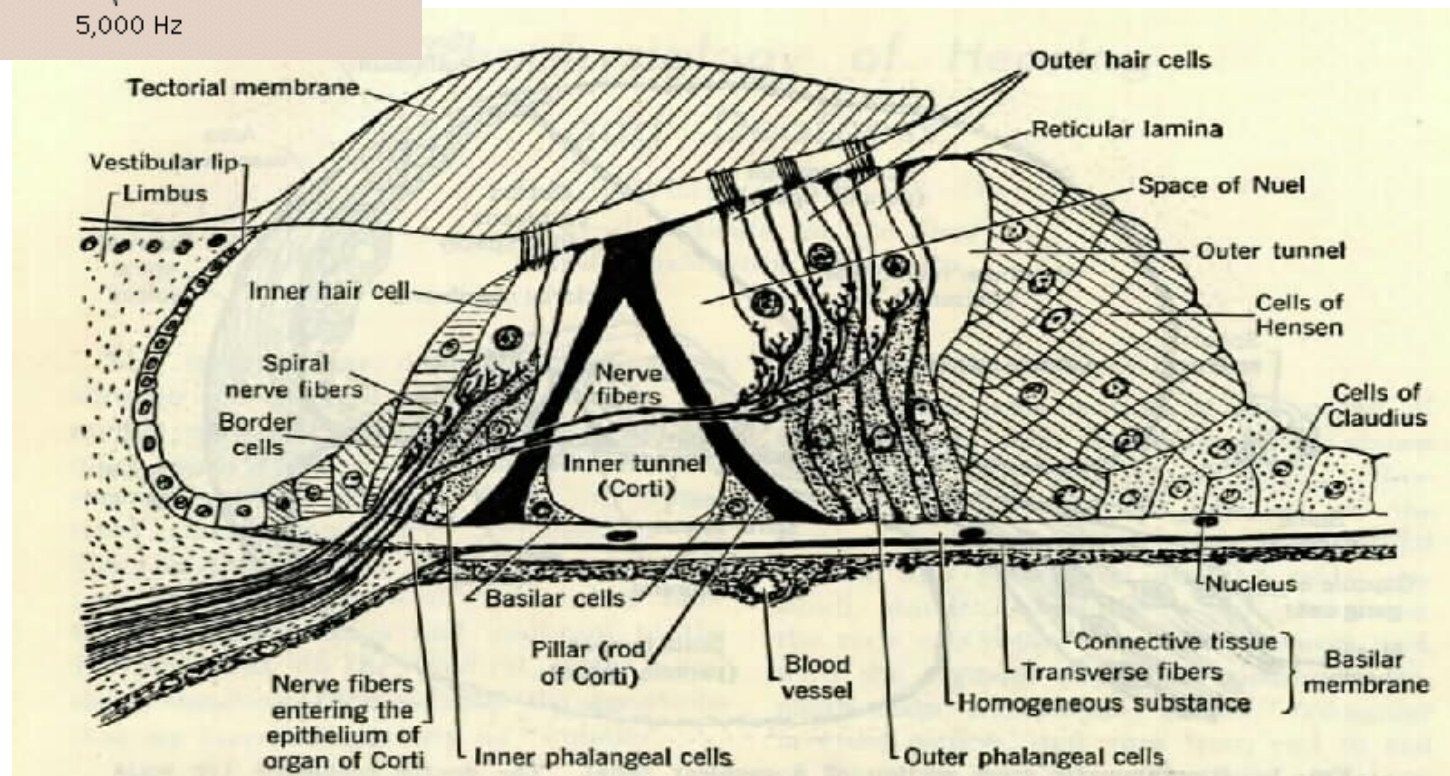
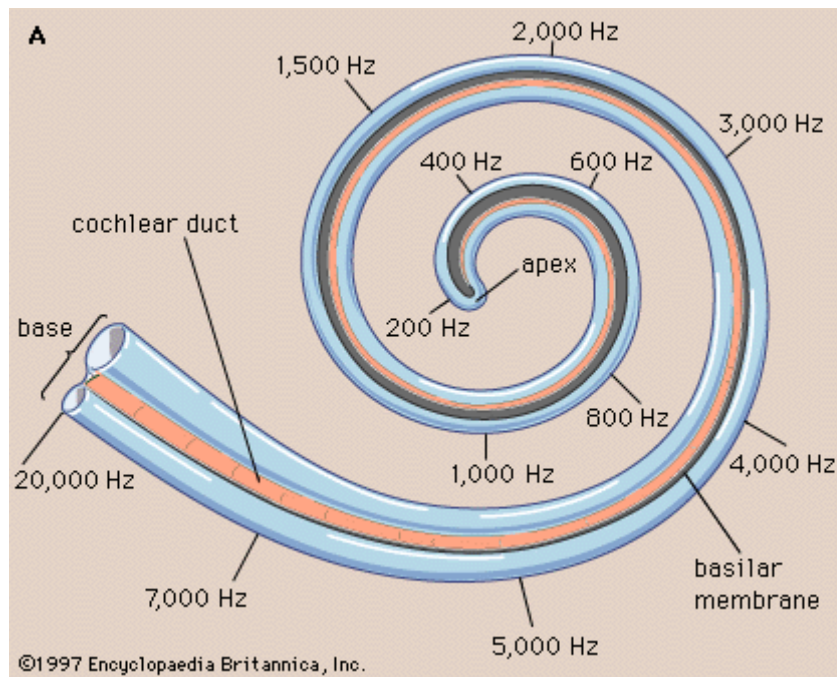


Outer Ear

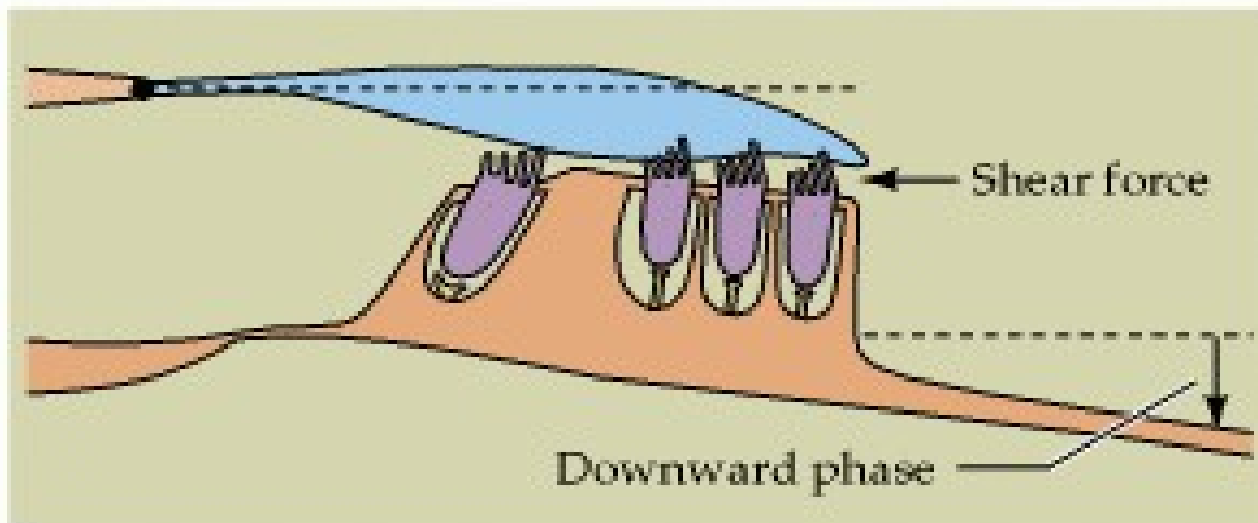
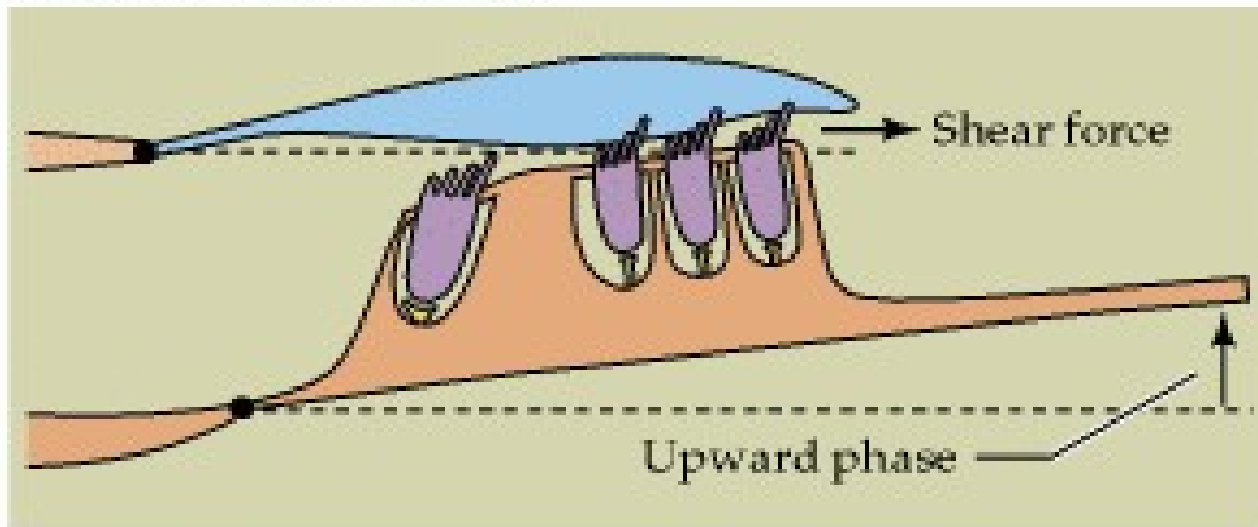
- the “Pinna” is not frequency flat.
Different frequencies are detected at different intensities.

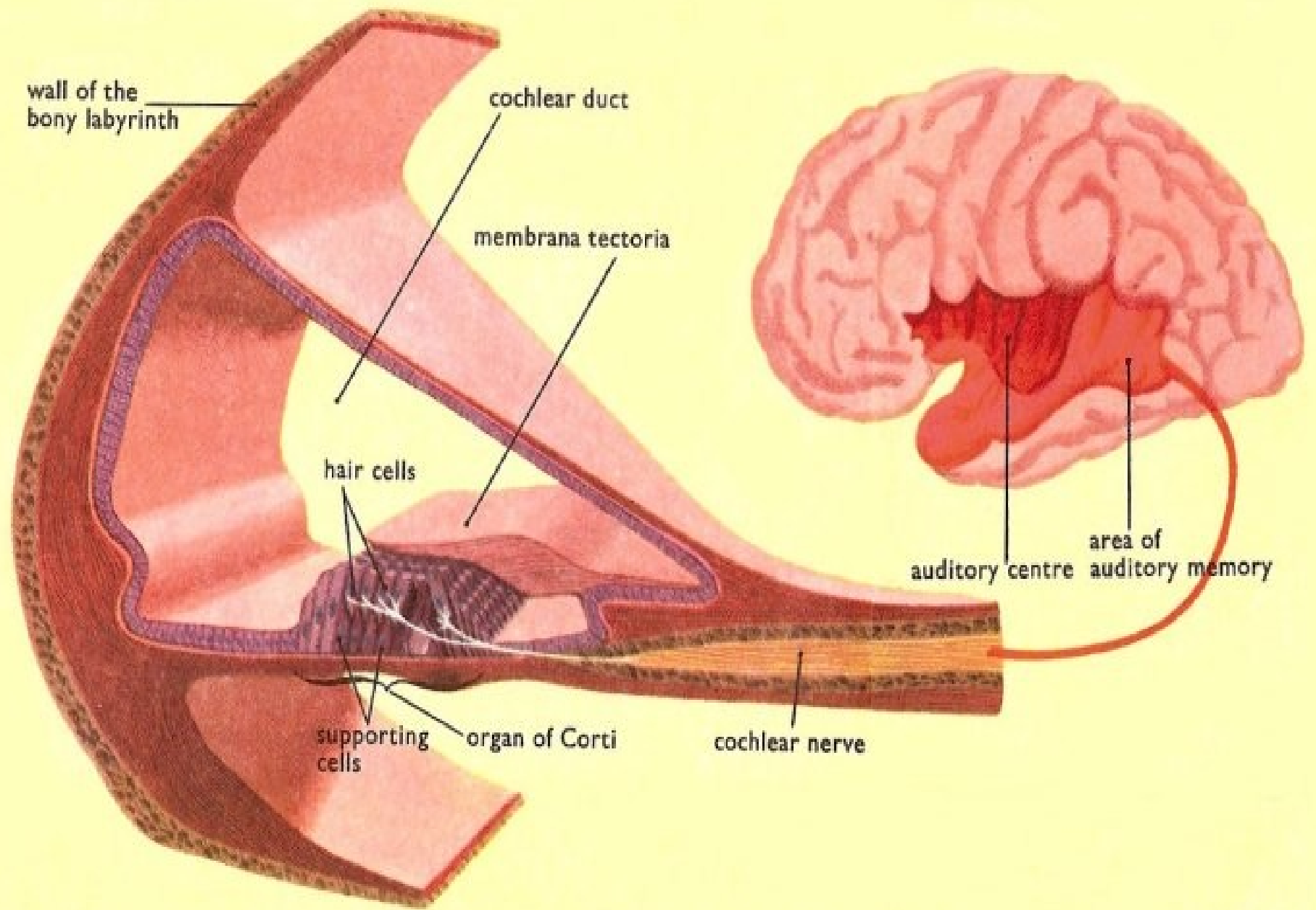


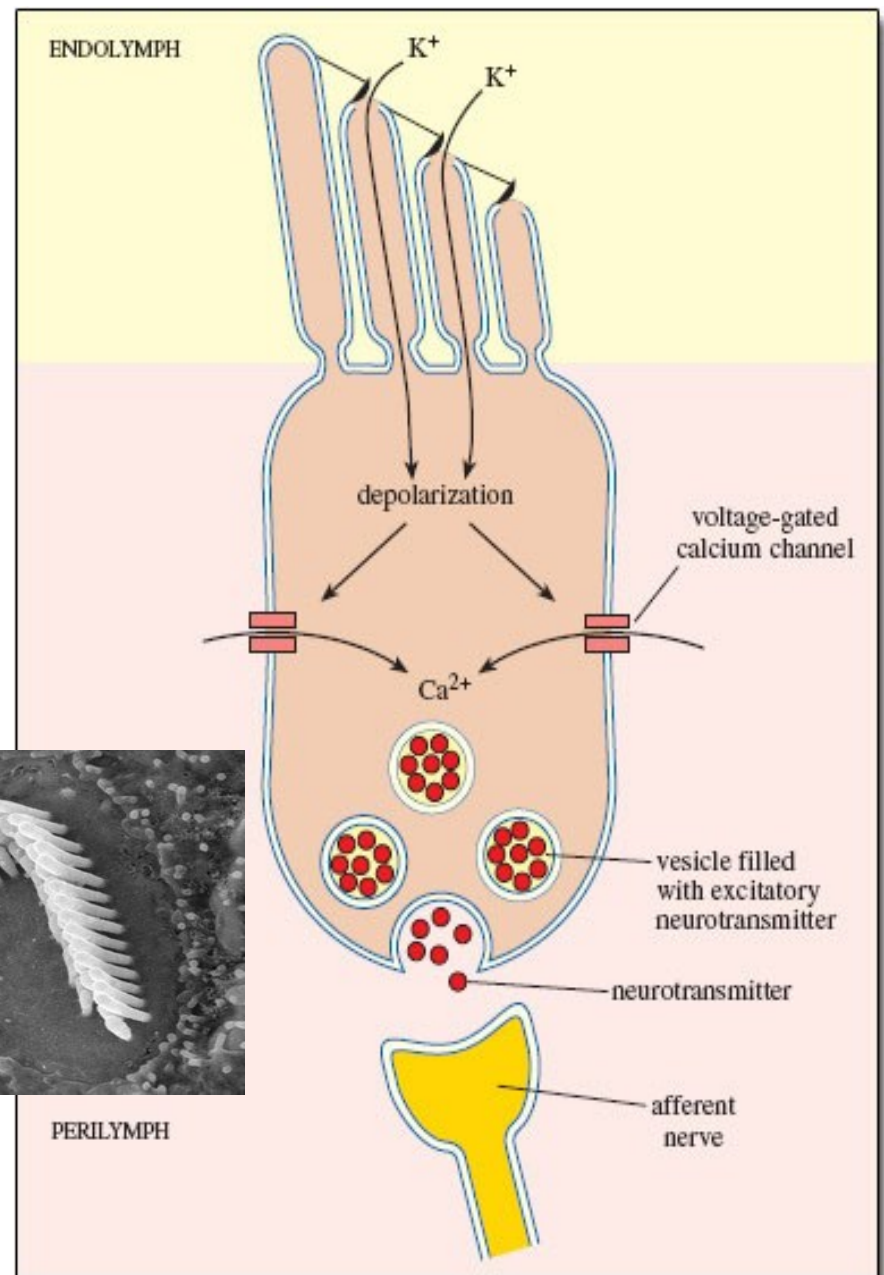
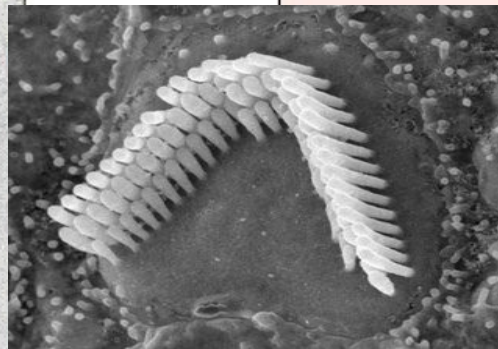
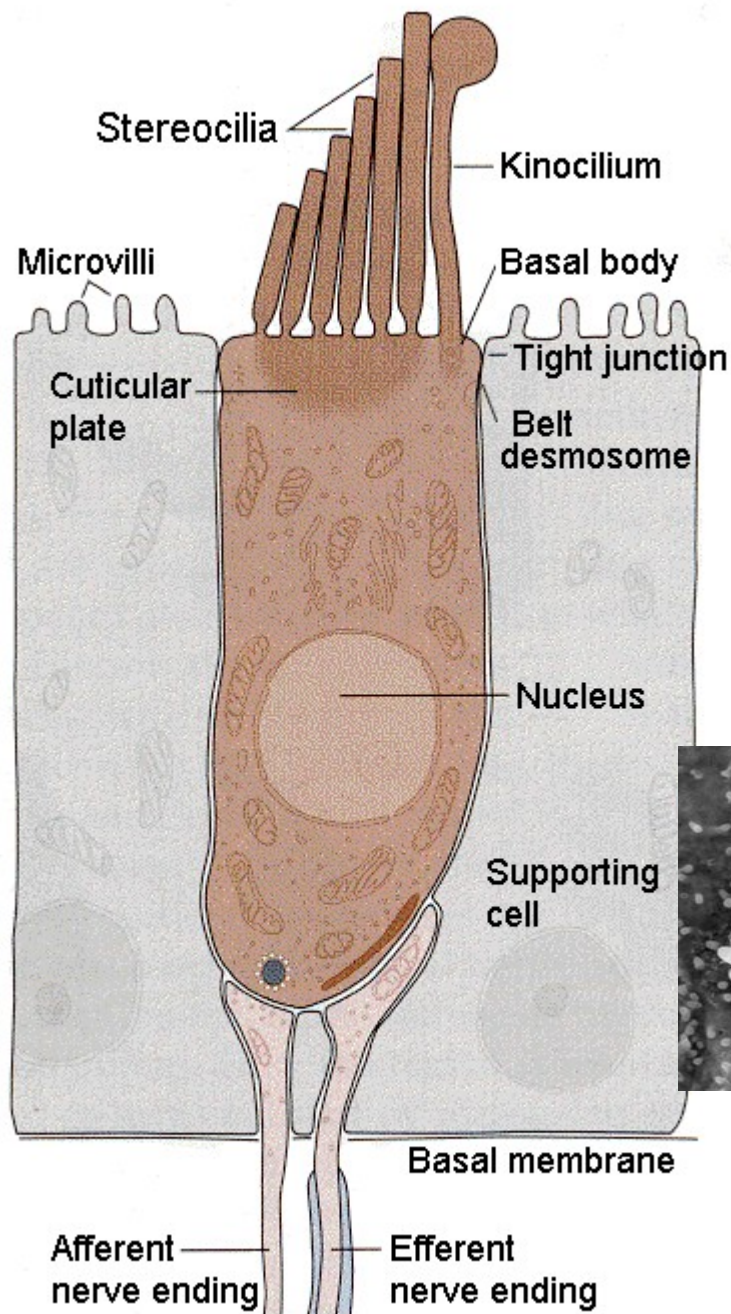


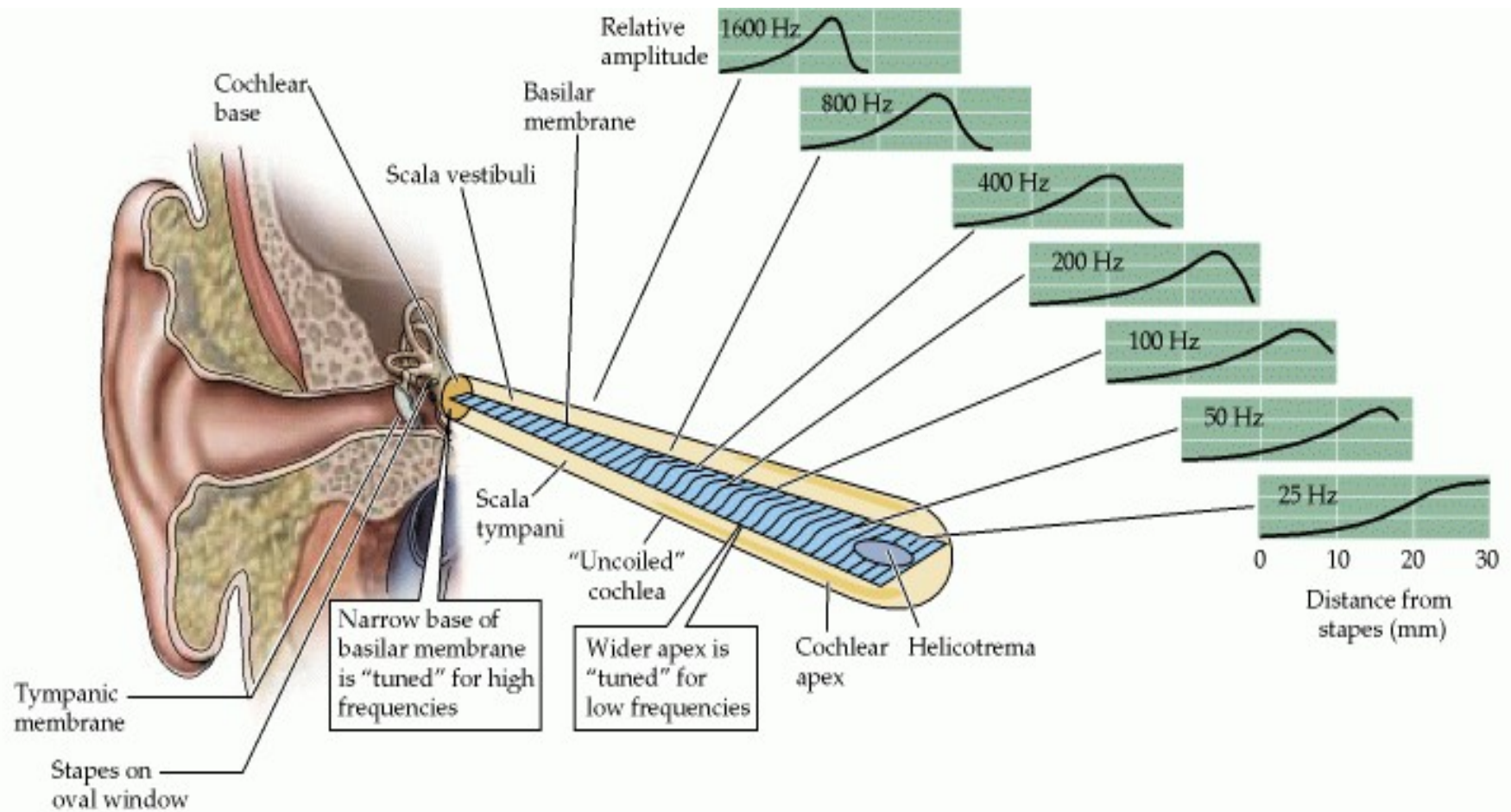


Sound-induced vibration



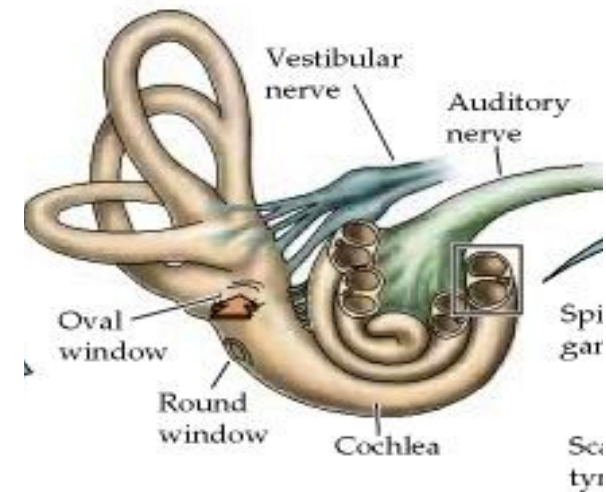
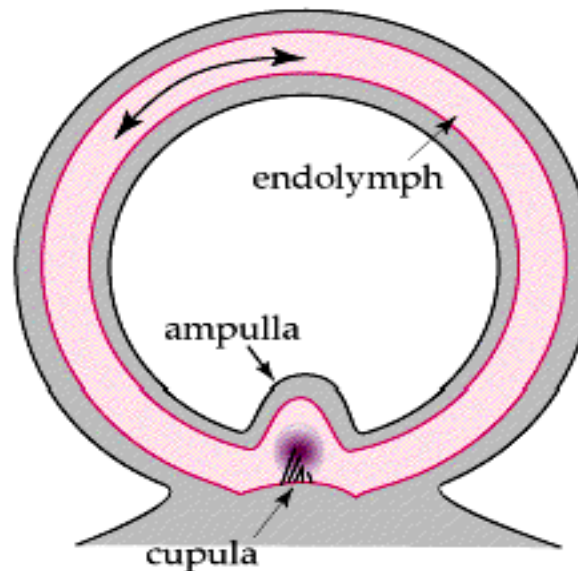
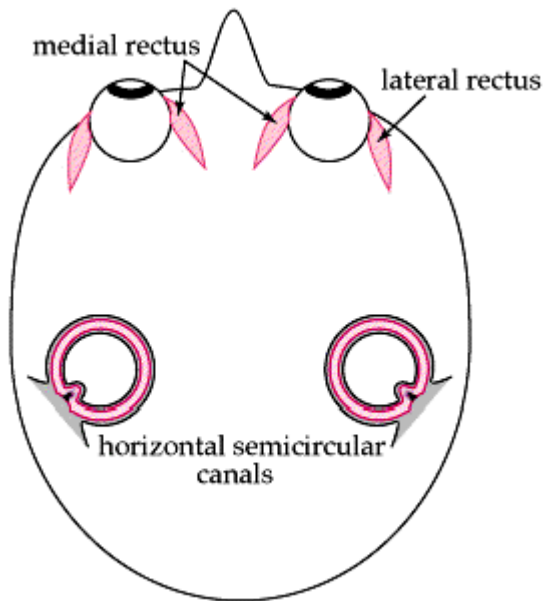






Three Gyroscopes in our Ears !

The **semicircular canals** detect angular **acceleration**. There are 3 canals, corresponding to the three dimensions in which you move, so that each canal detects motion in a single plane. Each canal is set up as shown below, as a continuous endolymph-filled hoop. The actual hair cells sit in a small swelling at the base called the ampulla.

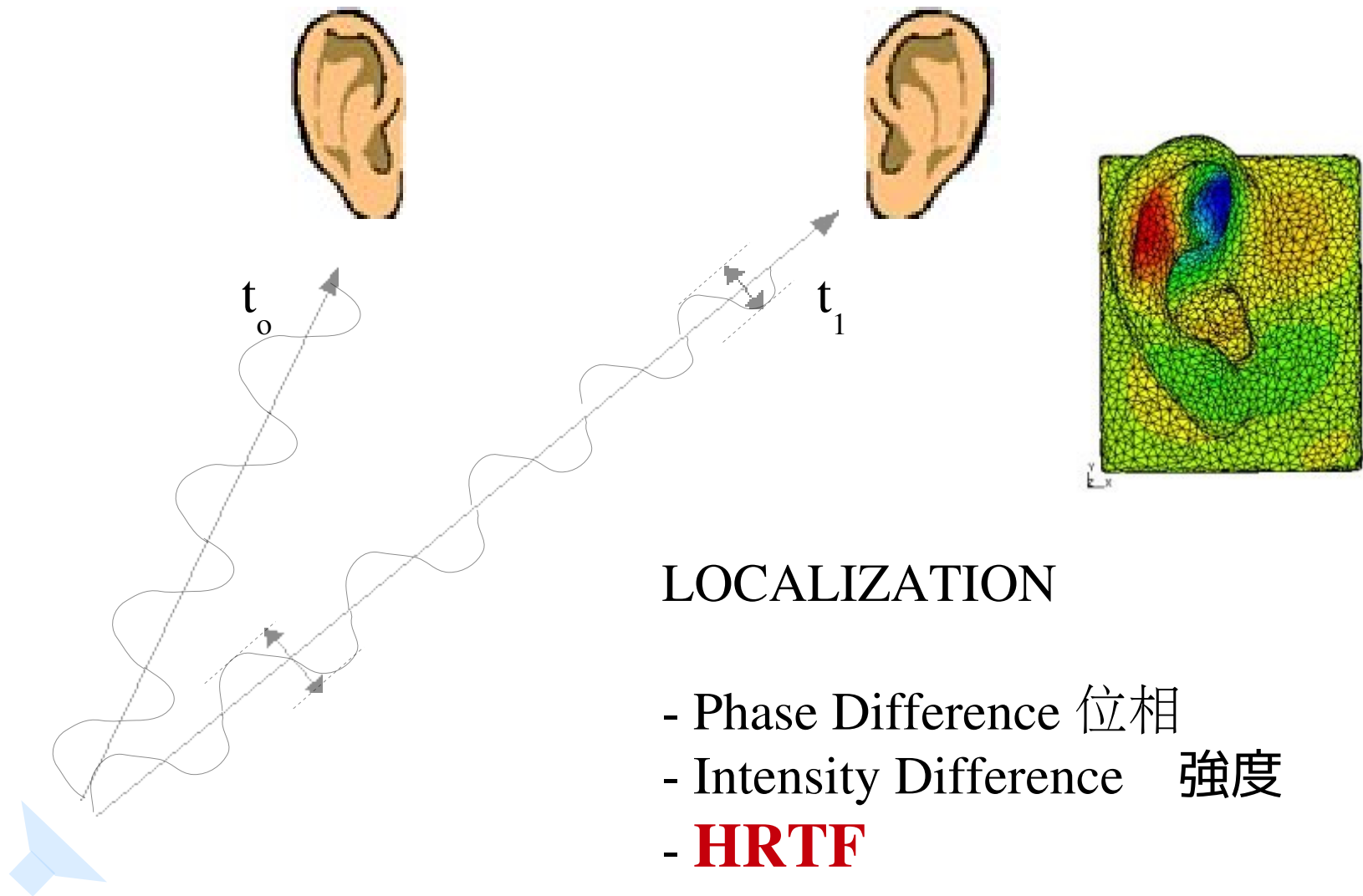


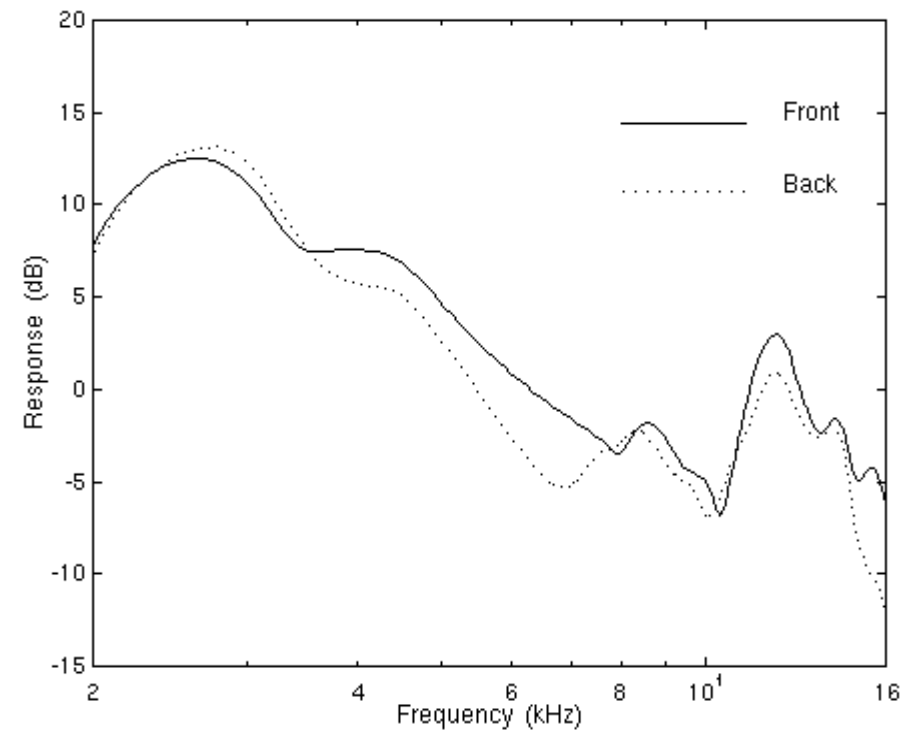
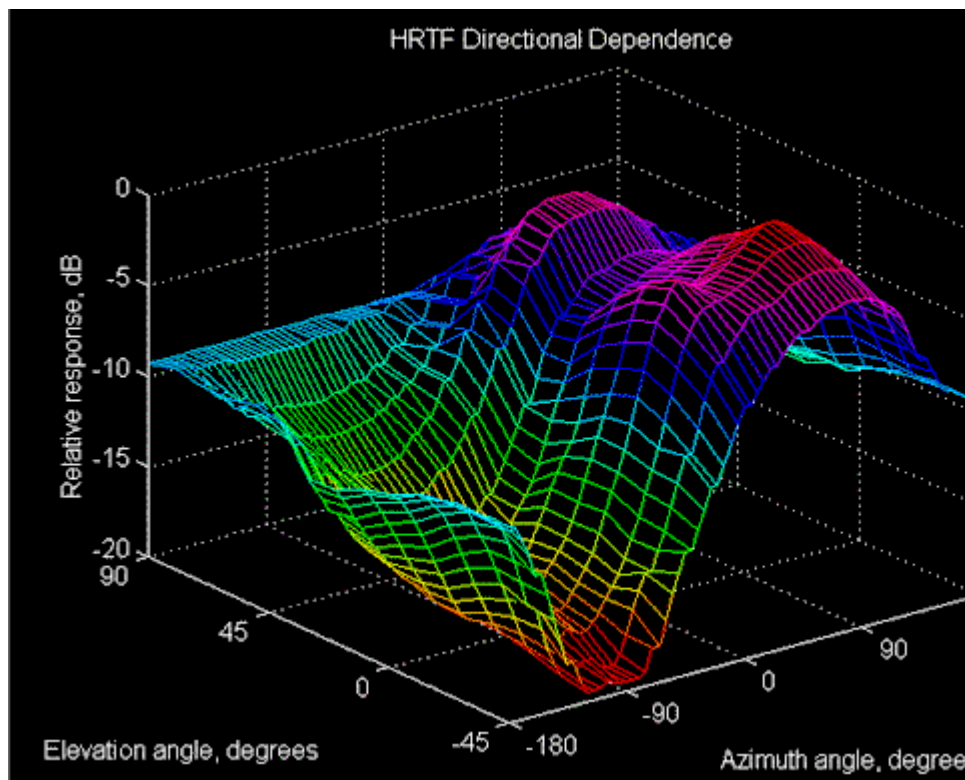
Localization of sound

The ability to estimate just where a sound is coming from, sound localization, is dependent on hearing ability of each of the two ears, and the exact quality of the sound. Since each ear lies on an opposite side of the head, a sound will reach the **closest ear first**, and its amplitude will be larger in that ear.

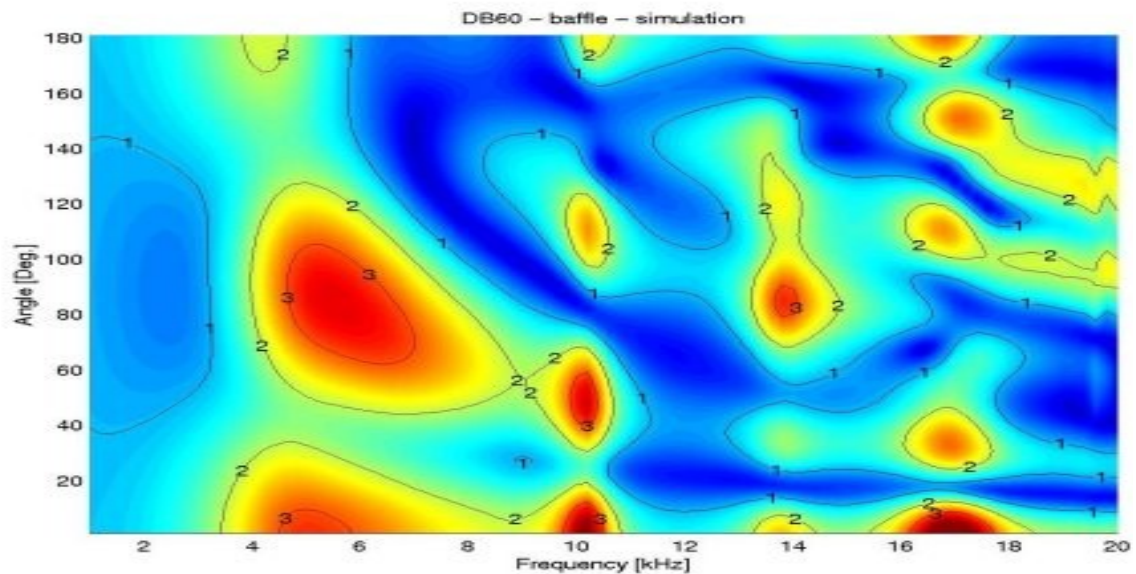
The shape of the **pinna** (outer ear) and of the head itself result in frequency-dependent variation in the amount of attenuation that a sound receives as it travels from the sound source to the ear. Furthermore, this variation depends not only on the **azimuthal angle** of the source, but also on its **elevation**. This variation is described as the head-related transfer function, or HRTF. As a result, humans can locate sound both in azimuth and altitude. Most of the brain's ability to localize sound depends on interaural (between ears) **intensity** differences and interaural **temporal**, or phase, differences. In addition, humans can also estimate the distance that a sound comes from, based primarily on how **reflections** in the environment modify the sound, for example, as in room reverberation.

Human echolocation is a technique used by some blind humans to navigate within their environment by listening for echoes of clicking or tapping sounds that they emit.





Depending on the angle we have different acoustical response.



Head-Related Transfer Functions (HRTFs)

Frequency Domain: Magnitude Spectra

